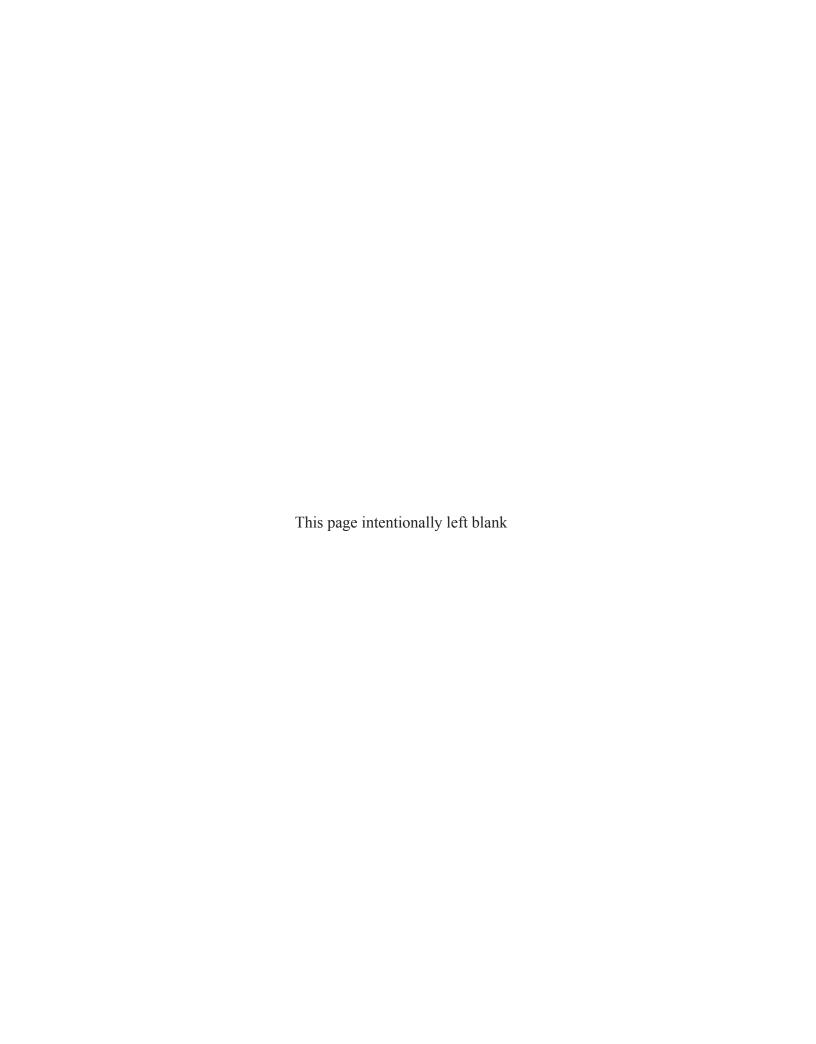




# college physics

a strategic approach 4e





### **Useful Data**

Pl	lanetary	data	and	gravity

$M_{\rm e}$	Mass of the earth	$5.98 \times 10^{24} \mathrm{kg}$
$R_{\rm e}$	Radius of the earth	$6.37 \times 10^6 \mathrm{m}$
g	Free-fall acceleration	$9.80 \text{ m/s}^2$

 $6.67 \times 10^{-11} \,\mathrm{N} \cdot \mathrm{m}^2/\mathrm{kg}^2$ GGravitational constant

### **Thermodynamics**

$k_{ m B}$	Boltzmann's constant	$1.38 \times 10^{-23} \text{J/K}$
R	Gas constant	8.31 J/mol • K

 $6.02 \times 10^{23}$  particles/mol  $-273^{\circ}$ C Avogadro's number  $N_{\rm A}$ 

 $T_0$ Absolute zero 101,300 Pa Standard atmosphere  $p_{\text{atm}}$ 

### Speeds of sound and light

$v_{\rm sound}$	Speed of sound in air at 20°C	343 m/s
c	Speed of light in vacuum	$3.00 \times 10^8 \text{m/s}$

### Particle masses

$m_{ m p}$	Mass of the proton (and the neutron)	$1.67 \times 10^{-27} \text{ kg}$
$m_{\rm n}$	Mass of the neutron	$1.67 \times 10^{-27} \text{ kg}$
$m_{ m e}$	Mass of the electron	$9.11 \times 10^{-31} \text{ kg}$

### **Electricity and magnetism**

K	Coulomb's law constant $(1/4\pi\epsilon_0)$	$8.99 \times 10^9 \mathrm{N} \cdot \mathrm{m}^2/\mathrm{C}^2$
$\epsilon_0$	Permittivity constant	$8.85 \times 10^{-12} \mathrm{C}^2/\mathrm{N} \cdot \mathrm{m}^2$
$\mu_0$	Permeability constant	$1.26 \times 10^{-6} \mathrm{T} \cdot \mathrm{m/A}$
e	Fundamental unit of charge	$1.60 \times 10^{-19} \mathrm{C}$

### Quantum and atomic physics

h	Planck's constant	$6.63 \times 10^{-34} \mathrm{J} \cdot \mathrm{s}$	$4.14 \times 10^{-15} \text{ eV} \cdot \text{s}$
$\hbar$	Planck's constant	$1.05 \times 10^{-34} \mathrm{J} \cdot \mathrm{s}$	$6.58 \times 10^{-16}  \text{eV} \cdot \text{s}$
$a_{\mathrm{B}}$	Bohr radius	$5.29 \times 10^{-11} \text{ m}$	

### **Common Prefixes**

### **Conversion Factors**

Prefix	Meaning	Length	Time
femto-	$10^{-15}$	1  in = 2.54  cm	1  day = 86,400  s
pico-	$10^{-12}$	1  mi = 1.609  km	1 year = $3.16 \times 10^7$ s
nano-	$10^{-9}$	1  m = 39.37  in	Force
micro-	$10^{-6}$	1  km = 0.621  mi	1 lb = 4.45 N
milli-	$10^{-3}$	Velocity	Pressure
centi-	$10^{-2}$	1  mph = 0.447  m/s	1 atm = $101.3 \text{ kPa} = 760 \text{ mm Hg}$
kilo-	$10^{3}$	1  m/s = 2.24  mph = 3.28  ft/s	$1 \text{ atm} = 101.5 \text{ kf a} = 700 \text{ mm f rg}$ $1 \text{ atm} = 14.7 \text{ lb/in}^2$
mega-	$10^{6}$	Mass and anaray	
giga-	$10^9$	Mass and energy	Rotation
terra-	$10^{12}$	$1 u = 1.661 \times 10^{-27} \text{ kg}$	$1 \text{ rad} = 180^{\circ}/\pi = 57.3^{\circ}$
		1  cal = 4.19  J	$1 \text{ rev} = 360^{\circ} = 2\pi \text{ rad}$
		$1 \text{ eV} = 1.60 \times 10^{-19} \text{ J}$	1  rev/s = 60  rpm

### **Greek Letters Used in Physics**

Alpha		$\alpha$	Nu		$\nu$
Beta		$\beta$	Pi		$\pi$
Gamma	Γ	γ	Rho		$\rho$
Delta	$\Delta$	δ	Sigma	$\sum$	$\sigma$
Epsilon		$\epsilon$	Tau		au
Eta		$\eta$	Phi	Φ	$\phi$
Theta	θ	$\theta$	Psi		$\psi$
Lambda		λ	Omega	$\Omega$	ω
Mii		11			

### **Mathematical Approximations**

Binomial approximation:
$(1+x)^n \approx 1 + nx \text{ if } x \ll 1$
Small-angle approximation:
$\sin \theta \approx \tan \theta \approx \theta$ and $\cos \theta \approx 1$ if $\theta \ll 1$ radian

### **Table of Problem-Solving Approaches**

PROBLEM-SOLVING APPROACH		
	Problem-solving approach	51
2.1	Motion with constant acceleration	54
3.1	Projectile motion problems	88
5.1	Equilibrium problems	135
5.2	Dynamics problems	139
6.1	Circular dynamics problems	180
7.1	Rotational dynamics problems	227
8.1	Static equilibrium problems	247
9.1	Conservation of momentum problems	290
10.1	Conservation of energy problems	328
11.1	Energy efficiency problems	357
12.1	Calorimetry problems	419
16.1	Standing waves	561
20.1	Electric forces and Coulomb's law	707
21.1	Conservation of energy in charge interactions	741
23.1	Resistor circuits	812
24.1	Magnetic-force problems	860
25.1	Electromagnetic induction	890

### **Table of Synthesis Boxes**

2.1 Describing motion in one dimension 49 3.1 Projectile motion 87 5.1 A catalog of forces 157 7.1 Linear and circular motion 213 7.2 Linear and rotational dynamics 225 9.1 Momentum and impulse 283 10.1 Energy and its conservation 331 14.1 Describing simple harmonic motion 493 15.1 Wave motion 528 15.2 Wave power and intensity 535 16.1 Standing wave modes 561 17.1 Double-slit interference and diffraction gratings 598 18.1 Lenses, mirrors, and their sign conventions 645 20.1 Two key electric fields 718 21.1 The parallel-plate capacitor: Potential and electric field 746 21.2 Potential of a point charge and a charged sphere 750 24.1 Fields from currents 851	SYNTHES	sis	PAGE
5.1 A catalog of forces  7.1 Linear and circular motion  7.2 Linear and rotational dynamics  9.1 Momentum and impulse  10.1 Energy and its conservation  14.1 Describing simple harmonic motion  15.1 Wave motion  15.2 Wave power and intensity  16.1 Standing wave modes  17.1 Double-slit interference and diffraction gratings  18.1 Lenses, mirrors, and their sign conventions  18.1 The parallel-plate capacitor: Potential and electric field  21.2 Potential of a point charge and a charged sphere  750	2.1	Describing motion in one dimension	49
7.1 Linear and circular motion 213 7.2 Linear and rotational dynamics 225 9.1 Momentum and impulse 283 10.1 Energy and its conservation 331 14.1 Describing simple harmonic motion 493 15.1 Wave motion 528 15.2 Wave power and intensity 535 16.1 Standing wave modes 561 17.1 Double-slit interference and diffraction gratings 598 18.1 Lenses, mirrors, and their sign conventions 645 20.1 Two key electric fields 718 21.1 The parallel-plate capacitor: Potential and electric field 746 21.2 Potential of a point charge and a charged sphere 750	3.1	Projectile motion	87
7.2 Linear and rotational dynamics 225 9.1 Momentum and impulse 283 10.1 Energy and its conservation 331 14.1 Describing simple harmonic motion 493 15.1 Wave motion 528 15.2 Wave power and intensity 535 16.1 Standing wave modes 561 17.1 Double-slit interference and diffraction gratings 598 18.1 Lenses, mirrors, and their sign conventions 645 20.1 Two key electric fields 718 21.1 The parallel-plate capacitor: Potential and electric field 746 21.2 Potential of a point charge and a charged sphere 750	5.1	A catalog of forces	157
9.1 Momentum and impulse 283 10.1 Energy and its conservation 331 14.1 Describing simple harmonic motion 493 15.1 Wave motion 528 15.2 Wave power and intensity 535 16.1 Standing wave modes 561 17.1 Double-slit interference and diffraction gratings 598 18.1 Lenses, mirrors, and their sign conventions 645 20.1 Two key electric fields 718 21.1 The parallel-plate capacitor: Potential and electric field 746 21.2 Potential of a point charge and a charged sphere 750	7.1	Linear and circular motion	213
10.1 Energy and its conservation 331 14.1 Describing simple harmonic motion 493 15.1 Wave motion 528 15.2 Wave power and intensity 535 16.1 Standing wave modes 561 17.1 Double-slit interference and diffraction gratings 598 18.1 Lenses, mirrors, and their sign conventions 645 20.1 Two key electric fields 718 21.1 The parallel-plate capacitor: Potential and electric field 746 21.2 Potential of a point charge and a charged sphere 750	7.2	Linear and rotational dynamics	225
14.1 Describing simple harmonic motion 493 15.1 Wave motion 528 15.2 Wave power and intensity 535 16.1 Standing wave modes 561 17.1 Double-slit interference and diffraction gratings 598 18.1 Lenses, mirrors, and their sign conventions 645 20.1 Two key electric fields 718 21.1 The parallel-plate capacitor: Potential and electric field 746 21.2 Potential of a point charge and a charged sphere 750	9.1	Momentum and impulse	283
15.1 Wave motion 528 15.2 Wave power and intensity 535 16.1 Standing wave modes 561 17.1 Double-slit interference and diffraction gratings 598 18.1 Lenses, mirrors, and their sign conventions 645 20.1 Two key electric fields 718 21.1 The parallel-plate capacitor: Potential and electric field 746 21.2 Potential of a point charge and a charged sphere 750	10.1	Energy and its conservation	331
15.2 Wave power and intensity  15.2 Standing wave modes  16.1 Standing wave modes  17.1 Double-slit interference and diffraction gratings  18.1 Lenses, mirrors, and their sign conventions  18.1 Two key electric fields  18.1 The parallel-plate capacitor: Potential and electric field  18.1 The parallel-plate capacitor: Potential and electric field	14.1	Describing simple harmonic motion	493
16.1 Standing wave modes 561  17.1 Double-slit interference and diffraction gratings 598  18.1 Lenses, mirrors, and their sign conventions 645  20.1 Two key electric fields 718  21.1 The parallel-plate capacitor: Potential and electric field 746  21.2 Potential of a point charge and a charged sphere 750	15.1	Wave motion	528
17.1 Double-slit interference and diffraction gratings 598 18.1 Lenses, mirrors, and their sign conventions 645 20.1 Two key electric fields 718 21.1 The parallel-plate capacitor: Potential and electric field 746 21.2 Potential of a point charge and a charged sphere 750	15.2	Wave power and intensity	535
18.1 Lenses, mirrors, and their sign conventions 645 20.1 Two key electric fields 718 21.1 The parallel-plate capacitor: Potential and electric field 746 21.2 Potential of a point charge and a charged sphere 750	16.1	Standing wave modes	561
20.1 Two key electric fields 718  21.1 The parallel-plate capacitor: Potential and electric field 746  21.2 Potential of a point charge and a charged sphere 750	17.1	Double-slit interference and diffraction gratings	598
21.1 The parallel-plate capacitor: Potential and electric field 746 21.2 Potential of a point charge and a charged sphere 750	18.1	Lenses, mirrors, and their sign conventions	645
electric field 746  21.2 Potential of a point charge and a charged sphere 750	20.1	Two key electric fields	718
21.2 Potential of a point charge and a charged sphere 750	21.1		
_ ii _ i o i o i o i o i o i o i o i o i			,
<b>24.1 Fields from currents</b> 851	21.2	Potential of a point charge and a charged sphere	750
	24.1	Fields from currents	851
25.1 Electromagnetic waves 896	25.1	Electromagnetic waves	896
26.1 AC circuit elements 931	26.1	AC circuit elements	931
30.1 Nuclear decay modes 1066	30.1	Nuclear decay modes	1066

### **Table of Math Relationships**

MATH RELATIONSHIP	PAGE
Proportional relationships	39
Quadratic relationships	50
Inversely proportional	
relationships	116
Inverse-square relationships	191
Square-root relationships	401
Sinusoidal relationships	491
Exponential decay	503

Note for users of the two-volume edition: Volume 1 (pp. 1–583) includes Chapters 1–16. Volume 2 (pp. 584–1093) includes Chapters 17–30.

# **Brief Contents**

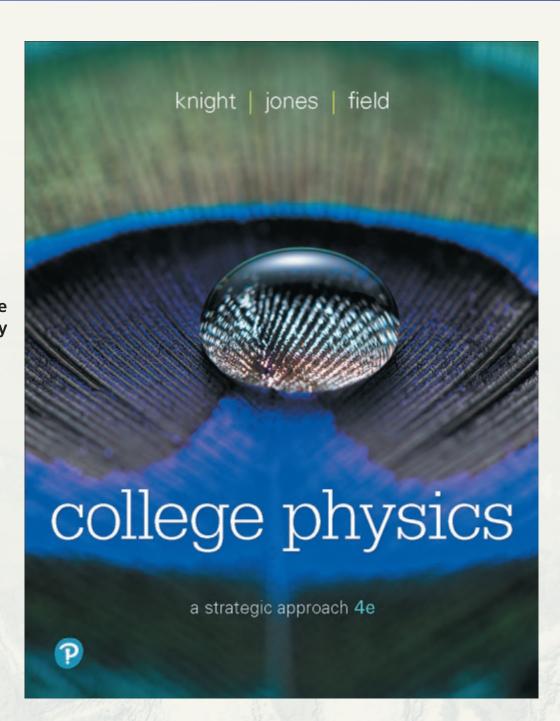
Atoms and Molecules 1019 Nuclear Physics 1054

30

### PART I Force and Motion Chapter 1 Representing Motion 4 Motion in One Dimension 32 2 Vectors and Motion in Two Dimensions 71 Forces and Newton's Laws of Motion 105 Applying Newton's Laws 134 Circular Motion, Orbits, and Gravity 175 7 Rotational Motion 205 Equilibrium and Elasticity 244 PART II **Conservation Laws** Momentum 278 Chapter 9 Energy and Work 309 10 11 Using Energy 354 PART III Properties of Matter Thermal Properties of Matter 396 Chapter 12 Fluids 441 13 **PART IV** Oscillations and Waves Oscillations 484 Chapter 14 Traveling Waves and Sound 518 15 Superposition and Standing Waves 549 PART V **Optics** Chapter 17 Wave Optics 586 18 Ray Optics 620 19 Optical Instruments 657 PART VI **Electricity and Magnetism** Chapter 20 Electric Fields and Forces 696 Electric Potential 734 21 22 Current and Resistance 774 23 Circuits 800 24 Magnetic Fields and Forces 838 25 EM Induction and EM Waves 879 AC Electricity 916 PART VII Modern Physics Chapter 27 Relativity 950 Quantum Physics 986 28 29

# **ENGAGE today's students**

For the fourth edition of College Physics: A Strategic Approach, we expand our focus from HOW students learn physics to WHY students study physics. We now make connections to biology and other sciences throughout the text to keep students engaged, presenting content that is relevant to today's students. This new edition is one of the best college physics book on the market for non-physics majors.





# More connections to life science

Build students' problem-solving skills in a context they care about while using real-life data and examples to keep their interest piqued.

### 13.7 The Circulatory System 🚯

### The Arteries and Capillaries

In the human body, blood pumped from the heart to the body starts its journey in a single large artery, the aorta. The flow then branches into smaller blood vessels, the large arteries that feed the head, the trunk, and the limbs. These branch into still smaller arteries, which then branch into a network of much smaller arterioles, which branch further into the capillaries. FIGURE 13.37 shows a schematic outline of the circulation, with average values for the diameters of the individual vessels, the total cross-section area of all of each type of vessel considered together, and the pressure in these vessels, assuming that the person is lying down so that there is no pressure change due to differences in elevation.

This preserved section of blood vessels shows the tremendous increase in number and in total area as blood vessels branch from large arteries to arterioles. One large artery gives rise to thousands of smaller vessels.

MEMI Topics of interest to life science students, such as the nature of the drag force at different scales and qualitative and quantitative descriptions of diffusion, provide current coverage of relevant topics based on the evolving consensus in the introductory physics for the life sciences community.



### 8.5 Forces and Torques in the Body 🚯

the application of physics to life sciences includes structural color in animals and plants, the electric sense of different animals, the circulatory system (13.7) and on forces and torques in the body (8.5).

Let's take your foot as the object of interest. When you stand on tiptoe, your foot pivots about your ankle. As shown in FIGURE 8.27, the forces on one foot are an upward force on your toes from the floor, a downward force on your ankle from the lower leg bone, and an upward force on the heel of your foot from your Achilles tendon. Suppose a 61 kg woman stands on one foot, on tiptoe, with the sole of her foot

Achilles tendon

Ankle pivot

15 cm

20 cm

FIGURE 8.27 Forces on the foot

making a 25° angle with the floor; the distances are as shown in Figure 8.27. What is the magnitude of the tension force in the tendon? By what fraction does this force exceed the woman's weight? What is the magnitude of the force in the ankle joint?

# create relevance to students' lives

### EXAMPLE 2.16 Finding the height of a leap (BIO)

A springbok is an antelope found in southern Africa that gets its name from its remarkable jumping ability. When a springbok is startled, it will leap straight up into the air—a maneuver called a "pronk." A particular springbok goes into a



crouch to perform a pronk. It then extends its legs forcefully, accelerating at 35 m/s<sup>2</sup> for 0.70 m as its legs straighten. Legs fully extended, it leaves the ground and rises into the air.

- a. At what speed does the springbok leave the ground?
- b. How high does it go?

**STRATEGIZE** This is a two-part problem. In the first phase of its motion, the springbok accelerates upward, reaching some maximum speed just as it leaves the ground. As soon as it does so, the springbok is subject to only the force of gravity, so it is in free fall. For both phases, we will use the constant-acceleration equations from Synthesis 2.1.

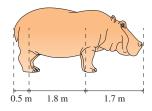
### **End-of-chapter problem**

sets now include real-life data and examples, helping students build transferable skills for their future courses and careers.

### **STRATEGIZE** step in Examples

shows students the "big picture" view before delving into the details. Classroom testing of this addition has shown it to be popular with students and effective in teaching problem-solving skills.

8. A hippo's body is 4.0 m long with front and rear feet Blo located as in Figure P8.8. The hippo carries 60% of its weight on its front feet. How far from its tail is the hippo's center of gravity?



**FIGURE P8.8** 

**NEW! Learning Objectives,** keyed to relevant end-of-chapter problems, help students check their understanding and guide them in choosing appropriate problems to optimize their study time.

### **Learning Objectives** After studying this chapter, you should be able to:

- Use motion diagrams to interpret motion. *Conceptual* Question 2.3; Problems 2.1, 2.2, 2.59
- Use and interpret motion graphs. Conceptual Questions 2.5, 2.13; Problems 2.4, 2.18, 2.19, 2.22, 2.62
- Calculate the velocity of an object. Conceptual Question 2.9; Problems 2.8, 2.15, 2.57
- Solve problems about an object in uniform motion. Problems 2.9, 2.10, 2.11, 2.13, 2.58

- Calculate the acceleration of an object. *Problems* 2.25, 2.27, 2.32, 2.33, 2.72
- Determine and interpret the sign of acceleration. *Conceptual* Questions 2.2, 2.8; Problem 2.50
- Use the problem-solving approach to solve problems of motion with constant acceleration and free fall. Problems 2.36, 2.40, 2.41, 2.47, 2.52, 2.75

# Prepare students for engagement



relatable content to engage students with what they are learning and promote curiosity for natural phenomena. These short videos present visually stimulating physical phenomena, pause throughout to address misconceptions, and ask conceptual questions about the physics at hand. Quantitative questions follow some of the videos and will be assignable in Mastering<sup>™</sup> Physics and embedded in the eText.

Prelecture Videos, presented by co-author Brian Jones, expand on the Chapter Previews, giving context, examples, and a chance for students to practice the concepts they are studying via short multiple-choice questions. **NEW! Qualitative and Quantitative prelecture videos** now available with assessment as well!

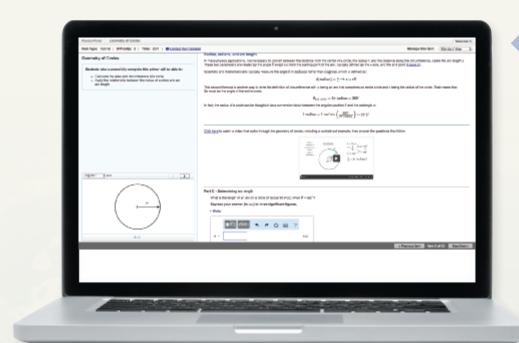




### NEW! eText, optimized for

mobile, seamlessly integrates videos and other rich media with the text and gives students access to their textbook anytime, anywhere. eText is available with Mastering Physics when packaged with new books, or as an upgrade students can purchase online.

# in lecture with interactive media



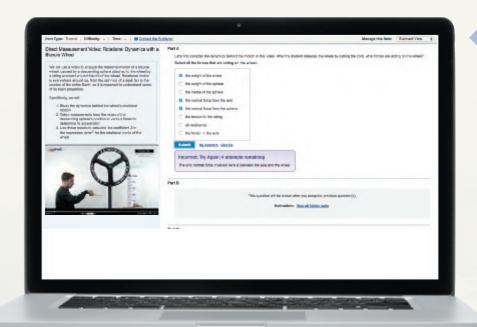
### **NEW!** The Physics Primer

relies on videos, hints, and feedback to refresh students' math skills in the context of physics and prepare them for success in the course. These tutorials can be assigned before the course begins as well as throughout the course. They ensure students practice and maintain their math skills, while tying together mathematical operations and physics analysis.

**Dynamic Study Modules (DSMs)** help students study effectively on their own by continuously assessing their activity and performance in real time and adapting to their level of understanding. The content focuses on definitions, units, and the key relationships for topics across all of mechanics and electricity and magnetism.



# **Enhance students' understanding when**



Videos are short videos that show real situations of physical phenomena. Grids, rulers, and frame counters appear as overlays, helping students to make precise measurements of quantities such as position and time. Students then apply these quantities along with physics concepts to solve problems and answer questions about the motion of the objects in the video.

Learning Catalytics™ helps generate class discussion, customize lectures, and promote peer-to-peer learning with real-time analytics. Learning Catalytics acts as a student response tool that uses students' smartphones, tablets, or laptops to engage them in more interactive tasks and thinking:

- NEW! Upload a full PowerPoint® deck for easy creation of slide questions.
- Monitor responses to find out where your students are struggling.
- Rely on real-time data to adjust your teaching strategy.
- Automatically group students for discussion, teamwork, and peer-to-peer learning.

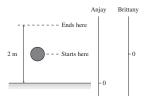


# they apply what they've learned

10-8 CHAPTER 10 · Energy and Work

### 10.6 Potential Energy

17. Below we see a 1 kg object that is initially 1 m above the ground and rises to a height of 2 m. Anjay and Brittany each measure its position but use a different coordinate system to do so. Fill in the table to show the initial and final gravitational potential energies and  $\Delta U$  as measured by Anjay and Brittany.



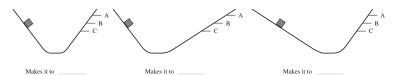
	$U_{\rm i}$	$U_{\mathrm{f}}$	$\Delta U$
Anjay			
Brittany			

18. Three balls of equal mass are fired simultaneously with *equal* speeds from the same height above the ground. Ball 1 is fired straight up, ball 2 is fired straight down, and ball 3 is fired horizontally. Rank in order, from largest to smallest, their speeds  $v_1$ ,  $v_2$ , and  $v_3$  as they hit the ground.



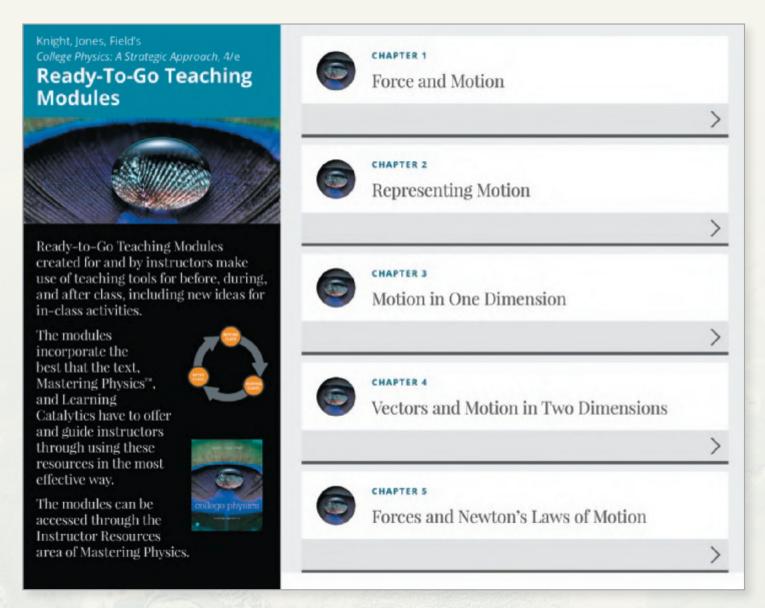
Order:
Explanation:

19. Below are shown three frictionless tracks. Ablock is released from rest at the position shown on the left. To which point does the block make it on the right before reversing direction and sliding back? Point B is the same height as the starting position.

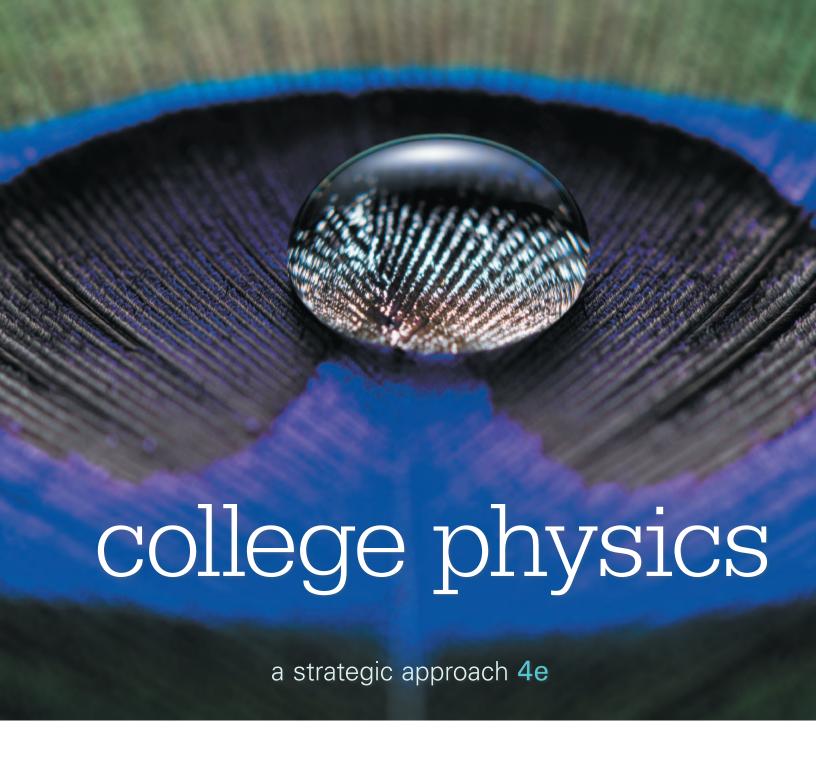


**A key component** of *College Physics: A Strategic Approach* is the accompanying **Student Workbook**. The workbook bridges the gap between textbook and homework problems by providing students the opportunity to learn and practice skills prior to using those skills in quantitative end-of-chapter problems, much as a musician practices technique separately from performance pieces. The workbook exercises, which are keyed to each section of the textbook, focus on developing specific skills, ranging from identifying forces and drawing free-body diagrams to interpreting field diagrams.

# Instructor tools help shape your course more efficiently



**NEW! Ready-to-Go Teaching Modules,** created for and by instructors, make use of teaching tools for before, during, and after class, including new ideas for in-class activities. The modules incorporate the best that the text, Mastering Physics, and Learning Catalytics have to offer and guide instructors through using these resources in the most effective way. The modules can be accessed through the Instructor Resources Area of Mastering Physics and as pre-built, customizable assignments.



randall d. knight

California Polytechnic State University, San Luis Obispo

brian jones | stuart field

Colorado State University

Colorado State University



Editor in Chief, Director Physical Science Courseware Portfolio:

Editor, Physics Courseware Portfolio Analyst:

Senior Content Producer:

Senior Content Developer:

Managing Producer:

Courseware Director, Content Development:

Jennifer Hart

Senior Analyst, Content Development, Science:Suzanne OlivierCourseware Editorial Assistant:Kristen StephensRich Media Content Producer:Dustin Hennessey

Full-Service Vendor: Nesbitt Graphics/Cenveo® Publisher Services

Copyeditor: Carol Reitz

Compositor: Nesbitt Graphics/Cenveo® Publisher Services

Art and Design Director: Mark Ong/Side By Side Studios

Interior/Cover Designer:tani hasegawaRights & Permissions Project Manager:Katrina MohnRights & Permissions Management:Ben FerriniPhoto Researcher:Dena Digilio Betz

Manufacturing Buyer: Stacey J. Weinberger/LSC Communications

Product Marketing Manager, Physical Sciences: Elizabeth Bell
Cover Photo Credit: MirageC/Getty

Copyright © 2019, 2017, 2015, 2010, 2007 Pearson Education, Inc. All Rights Reserved. Printed in the United States of America. This publication is protected by copyright, and permission should be obtained from the publisher prior to any prohibited reproduction, storage in a retrieval system, or transmission in any form or by any means, electronic, mechanical, photocopying, recording, or otherwise. For information regarding permissions, request forms and the appropriate contacts within the Pearson Education Global Rights & Permissions department, please visit www.pearsoned.com/permissions/.

Acknowledgements of third party content appear on pages C1–C4, which constitutes an extension of this copyright page.

PEARSON, ALWAYS LEARNING and Mastering<sup>TM</sup> Physics are exclusive trademarks in the U.S. and/or other countries owned by Pearson Education, Inc. or its affiliates.

Unless otherwise indicated herein, any third-party trademarks that may appear in this work are the property of their respective owners and any references to third-party trademarks, logos, or other trade dress are for demonstrative or descriptive purposes only. Such references are not intended to imply any sponsorship, endorsement, authorization, or promotion of Pearson's products by the owners of such marks, or any relationship between the owner and Pearson Education, Inc. or its affiliates, authors, licensees, or distributors.

Library of Congress Cataloging in Publication Control Number: 2017044155



# About the Authors



Randy Knight taught introductory physics for 32 years at Ohio State University and California Polytechnic State University, where he is Professor Emeritus of Physics. Professor Knight received a Ph.D. in physics from the University of California, Berkeley and was a post-doctoral fellow at the Harvard-Smithsonian Center for Astrophysics before joining the faculty at Ohio State University. It was at Ohio State that he began to learn about the research in physics education that, many years later, led to *Five Easy Lessons: Strategies for Successful Physics Teaching* and this book, as well as *Physics for Scientists and Engineers: A Strategic Approach*. Professor Knight's research interests are in the fields of laser spectroscopy and environmental science. When he's not in front of a computer, you can find Randy hiking, sea kayaking, playing the piano, or spending time with his wife Sally and their five cats.



Brian Jones has won several teaching awards at Colorado State University during his 30 years teaching in the Department of Physics. His teaching focus in recent years has been the College Physics class, including writing problems for the MCAT exam and helping students review for this test. In 2011, Brian was awarded the Robert A. Millikan Medal of the American Association of Physics Teachers for his work as director of the Little Shop of Physics, a hands-on science outreach program. He is actively exploring the effectiveness of methods of informal science education and how to extend these lessons to the college classroom. Brian has been invited to give workshops on techniques of science instruction throughout the United States and in Belize, Chile, Ethiopia, Azerbaijan, Mexico, Slovenia, Norway, and Namibia. Brian and his wife Carol have dozens of fruit trees and bushes in their yard, including an apple tree that was propagated from a tree in Isaac Newton's garden.



Stuart Field has been interested in science and technology his whole life. While in school he built telescopes, electronic circuits, and computers. After attending Stanford University, he earned a Ph.D. at the University of Chicago, where he studied the properties of materials at ultralow temperatures. After completing a postdoctoral position at the Massachusetts Institute of Technology, he held a faculty position at the University of Michigan. Currently at Colorado State University, Stuart teaches a variety of physics courses, including algebra-based introductory physics, and was an early and enthusiastic adopter of Knight's *Physics for Scientists and Engineers*. Stuart maintains an active research program in the area of superconductivity. Stuart enjoys Colorado's great outdoors, where he is an avid mountain biker; he also plays in local ice hockey leagues.

# Preface to the Instructor

In 2006, we published *College Physics: A Strategic Approach*, a new algebra-based physics textbook for students majoring in the biological and life sciences, architecture, natural resources, and other disciplines. As the first such book built from the ground up on research into how students can more effectively learn physics, it quickly gained widespread critical acclaim from professors and students alike. For this fourth edition, we have continued to build on the research-proven instructional techniques introduced in the first edition while working to make the book more useful for instructors, more relevant to the students who use it, and more connected to the other subjects they study.

### **Objectives**

Our primary goals in writing College Physics: A Strategic Approach are:

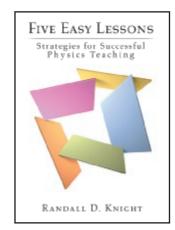
- To provide students with a textbook that's a more manageable size, less encyclopedic in its coverage, and better designed for learning.
- To integrate proven techniques from physics education research into the classroom in a way that accommodates a range of teaching and learning styles.
- To help students develop both quantitative reasoning skills and solid conceptual understanding, with special focus on concepts well documented to cause learning difficulties.
- To help students develop problem-solving skills and confidence in a systematic manner using explicit and consistent tactics and strategies.
- To motivate students by integrating real-world examples that are relevant to their majors—especially from biology, sports, medicine, the animal world—and that build upon their everyday experiences.
- To utilize proven techniques of visual instruction and design from educational research and cognitive psychology that improve student learning and retention and address a range of learner styles.

A more complete explanation of these goals and the rationale behind them can be found in Randy Knight's paperback book, *Five Easy Lessons: Strategies for Successful Physics Teaching*. Please request a copy from your local Pearson sales representative if it is of interest to you (ISBN 978-0-805-38702-5).



In previous editions of the text, we focused on *how* students learn physics. Each chapter was built from the ground up to present concepts and problem-solving strategies in an engaging and effective manner. In this edition, we are focusing on *why* students learn physics. This is a question our students often ask. Why should a biology major take physics? A student planning a career in medicine? This book is for a physics course, but it's a course that will generally be taken by students in other fields.

The central goal of this edition is to make the text more relatable to the students who will use it, to add examples, explanations, and problems that show physics at work in contexts the students will find engaging. We've considered extensive feedback from scores of instructors and thousands of students as we worked to enhance and improve the text, figures, and end-of-chapter problems. Instructors need not be specialists in the life sciences or other fields to appreciate the new material. We've done the work to connect physics to other disciplines so that instructors can use this material to engage their students while keeping their focus on the basic physics.



Making the text more relatable meant making significant changes throughout the book. These edits aren't cosmetic add-ons; they reflect a thorough reworking of each chapter. Changes include:

- Guided by an evolving consensus in the Introductory Physics for the Life Sciences community, we have included new sections on the nature of the drag force at different scales, qualitative and quantitative descriptions of diffusion, and other topics of interest to life science students.
- We have added a great deal of **new material** that stresses the application of physics to life science topics. For example, we have expanded our treatment of vision and vision correction, included new material on structural color in animals and plants and the electric sense of different animals, and added new sections on the circulatory system and on forces and torques in the body.
- We have made new connections between physics topics and other courses that students are likely to take. For example, a new section connects the concept of the conservation of energy to topics from chemistry, including ionization energy and the role of catalysts in reactions. We have continued this approach when we introduced the concept of electric potential energy.
- Hundreds of **new end-of-chapter questions and problems** show physics at work in realistic, interesting situations. We have replaced problems that are artificial and abstract with problems that use real data from research in life science fields, problems that show the physics behind modern technologies, and problems that use physics to explore everyday phenomena. We have used the wealth of data from Mastering TM Physics to make sure that we have problems of a wide range of difficulties for each topic and problem-solving approach. A rigorous blind-solving and accuracy cross-checking process has been used to check all new problems to be sure that they are clearly worded and correct in all details, that they are accompanied by carefully worked out solutions.
- New examples throughout the book use the concepts of the chapters to explore realistic situations of interest to the students—from how bees use electric fields to locate promising flowers to how a study of force and torque in the jaw explains why dogs have long snouts and cats don't.
- We have changed the **photos and captions** at the starts of the chapters and parts of the text to better interest and engage students. The questions that are raised at the starts of the chapters aren't rhetorical; they are questions that will be answered in the flow of the chapter.

We have also made a number of changes to make the text an even more effective tool for students:

- A new **STRATEGIZE** step in examples shows students the "big picture" view before we delve into the details. Classroom testing of this addition has shown it to be quite popular with students, and quite effective in teaching problem-solving skills.
- **Key Concept figures** encourage students to actively engage with key or complex figures by asking them to reason with a related STOP TO THINK question.
- Additional STOP TO THINK questions provide students with more crucial practice and concept checks as they go through the chapters. The solutions to these questions have been moved to a more prominent location.
- We now provide Learning Objectives keyed to relevant end-of-chapter problems to help students check their understanding and guide them in choosing appropriate problems to optimize their study time.
- Streamlined text and figures tighten and focus the presentation to more closely match student needs. We've scrutinized every figure, caption, discussion, and photo in order to enhance their clarity and focus their role.
- Increased emphasis on critical thinking, modeling, and reasoning, both in worked examples and in end-of-chapter problems, promotes these key skills. These skills are especially important for students who are taking the MCAT exam.

Expanded use of realistic and real-world data ensures students can make sense of answers that are grounded in the real world. Our examples and problems use real numbers and real data; they test different types of reasoning using equations, ratios, and graphs.

We have made many small changes to the flow of the text throughout, streamlining derivations and discussions, providing more explanation for complex concepts and situations, and reordering and reorganizing material so that each section and each chapter have a clearer focus. We have updated our treatment of entropy and the second law to better match current thinking. We have reordered the presentation of material on motion in two dimensions to be more logical. Every chapter has significant and meaningful changes, making this course especially relevant for today's students.

We know that students increasingly rely on sources of information beyond the text, and instructors are looking for quality resources that prepare students for engagement in lecture. The text will always be the central focus, but we have added additional media elements closely tied to the text that will enhance student understanding. In the Technology Update to the Second Edition, we added Class Videos, Video Tutor Solutions, and Video Tutor Demonstrations. In the Third Edition, we added an exciting new supplement, **Prelecture Videos**, short videos with author Brian Jones that introduce the topics of each chapter with accompanying assessment questions. In the front of this book, you'll find an illustrated walkthrough of the new media available in this technology update for the third edition:

- NEW! What the Physics? Videos bring new, relatable content to engage students with what they are learning and promote curiosity for natural phenomena. These short videos present visually stimulating physical phenomena and pause throughout to address misconceptions and ask conceptual questions about the physics at hand. The videos are embedded in the eText as well as assignable in Mastering Physics. Quantitative questions are also available for assignment.
- NEW! Direct Measurement Videos are short videos that show real situations of physical phenomena. Grids, rulers, and frame counters appear as overlays, helping students to make precise measurements of quantities such as position and time. Students then apply these quantities along with physics concepts to solve problems and answer questions about the motion of the objects in the video. The problems are assignable in Mastering Physics and can be used to replace or supplement traditional word problems, or as open-ended questions to help develop problem-solving skills.
- NEW! The Physics Primer relies on videos, hints, and feedback to refresh students' math skills in the context of physics and prepares them for success in the course. These tutorials can be assigned before the course begins or throughout the course as just-in-time remediation. They ensure students practice and maintain their math skills, while tying together mathematical operations and physics analysis.
- NEW! Quantitative Prelecture Videos are assignable, interactive videos that complement the Conceptual Prelecture Videos, giving students exposure to concepts before class and helping them learn how problems for those concepts are worked.
- NEW! Ready-to-Go Teaching Modules provide instructors with easy-to-use tools for teaching the toughest topics in physics. These modules demonstrate how your colleagues effectively use all the resources Pearson has to offer to accompany *College Physics: A Strategic Approach*, including, but not limited to, Mastering Physics items. Ready-to-Go Teaching Modules were created for and by instructors to provide easy-to-use assignments for before, during, and after class. Assets also include in-class activities and questions in Learning Catalytics<sup>TM</sup>.
- Dynamic Study Modules (DSMs) help students study on their own by continuously assessing their activity and performance in real time. Students complete a set of questions with a unique answer format that repeats each question until students can answer them all correctly and confidently.

- Dynamic Figure Videos in each chapter are one-minute videos based on figures from the textbook that depict important, but often challenging, physics principles.
- Video Tutor Solutions created by co-author Brian Jones are an engaging and helpful walkthrough of worked examples and select end-of-chapter (EOC) problems designed to help students solve problems for each main topic. Each chapter has seven Video Tutor Solutions.
- Prep questions aligned with the MCAT exam are based on the Foundational Concepts and Content Categories outlined by the Association of American Medical Colleges. These 140 new problems are assignable in Mastering Physics and available for self-study in the Study Area.
- Video Tutor Demonstrations feature "pause-and-predict" demonstrations of key physics concepts and incorporate assessment with answer-specific feedback.

### **Textbook Organization**

College Physics: A Strategic Approach is a 30-chapter text intended for use in a two-semester course. The textbook is divided into seven parts: Part I: Force and Motion, Part II: Conservation Laws, Part III: Properties of Matter, Part IV: Oscillations and Waves, Part V: Optics, Part VI: Electricity and Magnetism, and Part VII: Modern Physics.

Part I covers Newton's laws and their applications. The coverage of two fundamental conserved quantities, momentum and energy, is in Part II, for two reasons. First, the way that problems are solved using conservation laws—comparing an *after* situation to a *before* situation—differs fundamentally from the problem-solving strategies used in Newtonian dynamics. Second, the concept of energy has a significance far beyond mechanical (kinetic and potential) energies. In particular, the key idea in thermodynamics is energy, and moving from the study of energy in Part II into thermal physics in Part III allows the uninterrupted development of this important idea.

Optics (Part V) is covered directly after oscillations and waves (Part IV), but before electricity and magnetism (Part VI). Further, we treat wave optics before ray optics. Our motivations for this organization are twofold. First, wave optics is largely just an extension of the general ideas of waves; in a more traditional organization, students will have forgotten much of what they learned about waves by the time they get to wave optics. Second, optics as it is presented in introductory physics makes no use of the properties of electromagnetic fields. The documented difficulties that students have with optics are difficulties with waves, not difficulties with electricity and magnetism. There's little reason other than historical tradition to delay optics. However, the optics chapters are easily deferred until after Part VI for instructors who prefer that ordering of topics.

- Complete edition, with Mastering<sup>TM</sup> Physics and Student Workbook (ISBN 978-0-134-64149-2): Chapters 1–30.
- Books a la Carte edition, with Mastering<sup>TM</sup> Physics and Student Workbook (ISBN 978-0-134-64414-1)
- Complete edition, without Mastering<sup>TM</sup> Physics (ISBN 978-0-134-60903-4): Chapters 1–30.
- **Volume 1** without Mastering<sup>TM</sup> Physics (ISBN 978-0-134-61045-0): Chapters 1–16.
- **Volume 2** without Mastering<sup>TM</sup> Physics (ISBN 978-0-134-61046-7): Chapters 17–30.

Split your text the way you split your course! Log on to www.pearsonhighered.com/collections/educator-features.html and create your own splits of *College Physics: A Strategic Approach*, 4e, including *your* choice of chapters.

# Instructional Package

College Physics: A Strategic Approach, fourth edition, provides an integrated teaching and learning package of support material for students and instructors.

**NOTE** For convenience, most instructor supplements can be downloaded from the "Instructor Resources" area of Mastering Physics and the Instructor Resource Center (www.pearson.com/us/higher-education/customers/educators.html).

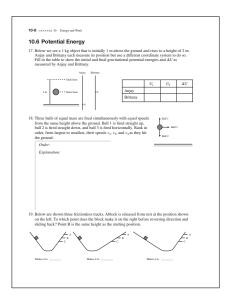
,		` 1		,
Supplement	Print	Online	Instructor or Student Supplement	Description
Mastering Physics with Pearson eText (ISBN 0134671023)		✓	Instructor and Student Supplement	This product features all of the resources of Mastering Physics in addition to the new Pearson eText 2.0. Now available on smartphones and tablets, Pearson eText 2.0 comprises the full text, including videos and other rich media.
Instructor's Solutions Manual (ISBN 0134796829)		1	Instructor Supplement	This comprehensive solutions manual contains complete solutions to all end-of-chapter questions and problems.
TestGen Test Bank (ISBN 0134702409)		1	Instructor Supplement	The Test Bank contains more than 2,000 high-quality problems, with a range of multiple-choice, true/false, short answer, and regular homework-type questions. Test files are provided in both TestGen® and Word format.
Instructor's Resource Materials	<b>√</b>	✓	Instructor Supplement	All art, photos, and tables from the book are available in JPEG format and as modifiable PowerPoints <sup>TM</sup> . In addition, instructors can access lecture outlines as well as "clicker" questions in PowerPoint format, editable content for key features, all the instructor's resources listed above, and solutions to the Student Workbook. Materials are accessible to download from the Instructor Resource area of Mastering Physics.
Student's Workbook Standard (CH1–30) (ISBN 0134609891X) Volume 1 (CH1–16) (ISBN 0134724828) Volume 2 (CH17–30) (ISBN 0134724801)	<b>√</b>		Student Supplement	For a more detailed description of the <i>Student's Workbook</i> , see page ix.
Student's Solutions Manual Volume 1 (CH1–16) (ISBN 0134704193) Volume 2 (CH17–30) (ISBN 0134724798)	<b>√</b>		Student Supplement	These solutions manuals contain detailed solutions to all of the odd-numbered end-of-chapter problems from the textbook.
Ready-to-Go Teaching Modules		J	Instructor Supplement	Ready-to-Go Teaching Modules provide instructors with easy-to-use tools for teaching the toughest topics in physics. Created by the authors and designed to be used before, during, and after class, these modules demonstrate how to effectively use all the book, media, and assessment resources that accompany <i>College Physics: A Strategic Approach 4e</i> .

### The Student Workbook

A key component of *College Physics: A Strategic Approach* is the accompanying *Student Workbook*. The workbook bridges the gap between textbook and homework problems by providing students the opportunity to learn and practice skills prior to using those skills in quantitative end-of-chapter problems, much as a musician practices technique separately from performance pieces. The workbook exercises, which are keyed to each section of the textbook, focus on developing specific skills, ranging from identifying forces and drawing free-body diagrams to interpreting field diagrams.

The workbook exercises, which are generally qualitative and/or graphical, draw heavily upon the physics education research literature. The exercises deal with issues known to cause student difficulties and employ techniques that have proven to be effective at overcoming those difficulties. Also included are *jeopardy problems* that ask students to work backward from equations to physical situations, enhancing their understanding and critical thinking skills. The workbook exercises can be used in-class as part of an active-learning teaching strategy, in recitation sections, or as assigned homework. More information about effective use of the *Student Workbook* can be found in the *Instructor's Guide* in the Ready-to-Go modules.

Available versions: Standard Edition (ISBN 978-0-134-60989-8): Chapters 1-30, Volume 1 (ISBN 978-0-134-72482-9): Chapters 1–16, and Volume 2 (978-0-134-72480-5): Chapters 17–30.



### Acknowledgments

We have relied upon conversations with and, especially, the written publications of many members of the physics education community. Those who may recognize their influence include the late Arnold Arons, Uri Ganiel, Fred Goldberg, Ibrahim Halloun, Paula Heron, David Hestenes, the late Leonard Jossem, Jill Larkin, Priscilla Laws, John Mallinckrodt, Richard Mayer, Lillian McDermott and members of the Physics Education Research Group at the University of Washington, Edward "Joe" Redish, Fred Reif, Rachel Scherr, Bruce Sherwood, David Sokoloff, Ronald Thornton, Sheila Tobias, Alan Van Heuvelen, Carl Wieman, and Michael Wittman.

We are very grateful to Larry Smith for the difficult task of writing the *Instructor Solutions Manual;* to Scott Nutter for writing out the Student Workbook answers; to Wayne Anderson, Jim Andrews, Nancy Beverly, David Cole, Karim Diff, Jim Dove, Marty Gelfand, Kathy Harper, Charlie Hibbard, Robert Lutz, Matt Moelter, Kandiah Manivannan, Ken Robinson, Cindy Schwarz-Rachmilowitz, and Rachel Jones for their contributions to the end-of-chapter questions and problems; to Wayne again for helping with the Test Bank questions; and to Steven Vogel for his careful review of the biological content of many chapters and for helpful suggestions.

We especially want to thank Editor-in-Chief, Director Physical Science Courseware Portfolio, Jeanne Zalesky; Editor, Physics Courseware Portfolio Analyst, Darien Estes; Courseware Director, Content Development, Jennifer Hart; Senior Analyst, Courseware Development, Suzanne Olivier; Senior Content Producer, Martha Steele; and all the other staff at Pearson for their enthusiasm and hard work on this project. Having a diverse author team is one of the strengths of this

book, but it has meant that we rely a great deal on Darien to help us keep to a single focus. Special thanks is due Martha for her keen attention to all details, careful scheduling and shepherding of all the elements of this complex project, and gentle prodding to keep everything moving forward.

Rose Kernan and the team at Nesbitt Graphics/Cenveo, copy editor Carol Reitz, and photo researcher Dena Digilio Betz get much credit for making this complex project all come together. In addition to the reviewers and classroom testers listed below, who gave invaluable feedback, we are particularly grateful to Ansel Foxley for his close scrutiny of every word, symbol, number, and figure.

Randy Knight: I would like to thank my Cal Poly colleagues for many valuable conversations and suggestions. I am endlessly grateful to my wife Sally for her love, encouragement, and patience, and to our many cats for nothing in particular other than being cats.

Brian Jones: I would like to thank my fellow AAPT and PIRA members for their insight and ideas, the students and colleagues who are my partners in the Little Shop of Physics, the students in my College Physics classes who teach me so much about the world, and the team at Pearson who help me develop as an educator and writer. Most of all, I thank my wife Carol, my best friend and gentlest editor, whose love makes the journey worthwhile.

**Stuart Field:** I would like to thank my wife Julie and my children, Sam and Ellen, for their love, support, and encouragement.

### **Reviewers and Classroom Testers**

### **Reviewers for the Fourth Edition**

Eduardo Araujo, Miami Dade College
Landon Bellavia, The University of Findlay
John Calarco, University of New Hampshire
Josh Colwell, University of Central Florida
Daniel Constantino, Pennsylvania State University
Chad Davies, Gordon College
Kimberly Fermoyle, Elmhurst College
Lilit Haroyan, Los Angeles Mission College
Tracy Hodge, Berea College
Kathleen Johnston, Louisiana Tech University
Wafaa Khattou, Valencia College West
Elena Kuchina, Thomas Nelson Community College

Ravi Kumar, Wayne Community College, Goldsboro
Jorge Lopez, University of Texas
Luiz Manzoni, Concordia College
Dario Martinez, Lone Star College
John McClain, Temple College
Irina Perevalova, Middle Tennessee State University
Amy Pope, Clemson University
Firouzeh Sabri, University of Memphis
Chandralekha Singh, University of Pittsburgh
Brenda Skoczelas, Lake Sumter State College
Valeriia Starovoitova, Idaho State University
Susa Stonedahl, St. Ambrose University

Ulrich Zurcher, Cleveland State University

### **Reviewers of Previous Editions**

Special thanks go to our third edition review panel: Taner Edis, Marty Gelfand, Jason Harlow, Charlie Hibbard, Jeff Loats, Amy Pope, and Bruce Schumm.

David Aaron, South Dakota State University Susmita Acharya, Cardinal Stritch University Ugur Akgun, University of Iowa Ralph Alexander, University of Missouri-Rolla Kyle Altmann, Elon University Donald Anderson, Ivy Tech Michael Anderson, University of California—San Diego Steve Anderson, Montana Tech James Andrews, Youngstown State University Charles Ardary, Edmond Community College Charles Bacon, Ferris State University John Barry, Houston Community College David H. Berman, University of Northern Iowa Phillippe Binder, *University of Hawaii—Hilo* Jeff Bodart, Chipola College James Boger, Flathead Valley Community College Richard Bone, Florida International University James Borgardt, Juniata College

Daniela Bortoletto, *Purdue University*Don Bowen, *Stephen F. Austin State University*Asa Bradley, *Spokane Falls Community College* 

Elena Brewer, SUNY at Buffalo
Dieter Brill, University of Maryland
Hauke Busch, Augusta State University
Kapila Castoldi, Oakland University

Raymond Chastain, Louisiana State University Michael Cherney, Creighton University Lee Chow, University of Central Florida

Song Chung, William Paterson University Alice Churukian, Concordia College

Christopher M. Coffin, *Oregon State University* John S. Colton, *Brigham Young University* 

Kristi Concannon, Kings College

Teman Cooke, Georgia Perimeter College at Lawrenceville Daniel J. Costantino, The Pennsylvania State University

Jesse Cude, Hartnell College

Melissa H. Dancy, University of North Carolina at Charlotte

Loretta Dauwe, University of Michigan—Flint

Mark Davenport, San Antonio College

Chad Davies, Gordon College Lawrence Day, Utica College

Carlos Delgado, Community College of Southern Nevada

David Donovan, Northern Michigan University
James Dove, Metropolitan State University of Denver
Archana Dubey, University of Central Florida

Andrew Duffy, *Boston University* Taner Edis, *Truman State University* 

Ralph Edwards, Lurleen B. Wallace Community College

Steve Ellis, University of Kentucky

Paula Engelhardt, Tennessee Technical University Davene Eryes, North Seattle Community College

Gerard Fasel, *Pepperdine University* Luciano Fleischfresser, *OSSM Autry Tech* 

Cynthia Galovich, *University of Northern Colorado*Bertram Gamory, *Monroe Community College*Sambandamurthy Ganapathy, *SUNY at Buffalo*Delena Gatch, *Georgia Southern University*Richard Gelderman, *Western Kentucky University* 

Martin Gelfand, Colorado State University
Terry Golding, University of North Texas
Robert Gramer, Lake City Community College
William Gregg, Louisiana State University
Paul Gresser, University of Maryland

Robert Hagood, Washtenaw Community College

Jason Harlow, *University of Toronto*Heath Hatch, *University of Massachusetts* 

Carl Hayn, Santa Clara University

James Heath, Austin Community College

Zvonko Hlousek, California State University Long Beach

Greg Hood, Tidewater Community College

Sebastian Hui, Florence-Darlington Technical College

Eric Hudson, The Pennsylvania State University

Joey Huston, Michigan State University

David Iadevaia, Pima Community College-East Campus

Fred Jarka, Stark State College

Ana Jofre, University of North Carolina—Charlotte

Daniel Jones, Georgia Tech

Erik Jensen, *Chemeketa Community College* Todd Kalisik, *Northern Illinois University* Ju H. Kim, *University of North Dakota* 

Armen Kocharian, California State University Northridge

J. M. Kowalski, University of North Texas Laird Kramer, Florida International University Christopher Kulp, Eastern Kentucky University Richard Kurtz, Louisiana State University Kenneth Lande, University of Pennsylvania Tiffany Landry, Folsom Lake College

Todd Leif, *Cloud County Community College*John Levin, *University of Tennessee—Knoxville*John Lindberg, *Seattle Pacific University* 

Jeff Loats, Metropolitan State University of Denver

Rafael López-Mobilia, The University of Texas at San Antonio

Robert W. Lutz, *Drake University* Lloyd Makorowitz, *SUNY Farmingdale* Colleen Marlow, *Rhode Island College* Eric Martell, *Millikin University* 

Mark Masters, Indiana University—Purdue

John McClain, Temple College

Denise Meeks, *Pima Community College* Henry Merrill, *Fox Valley Technical College* Mike Meyer, *Michigan Technological University* 

Karie Meyers, *Pima Community College* Tobias Moleski, *Nashville State Tech* April Moore, *North Harris College* Gary Morris, *Rice University* 

Krishna Mukherjee, Slippery Rock University

Charley Myles, *Texas Tech University* Meredith Newby, *Clemson University* 

David Nice, Bryn Mawr

Fred Olness, Southern Methodist University Charles Oliver Overstreet, San Antonio College

Paige Ouzts, Lander University

Russell Palma, Minnesota State University—Mankato Richard Panek, Florida Gulf Coast University Joshua Phiri, Florence-Darling Technical College Iulia Podariu, University of Nebraska at Omaha David Potter, Austin Community College

Promod Pratap, University of North Carolina—Greensboro

Michael Pravica, University of Nevada, Las Vegas

Earl Prohofsky, *Purdue University* 

Marilyn Rands, Lawrence Technological University

Andrew Rex, *University of Puget Sound* Andrew Richter, *Valparaiso University* 

William Robinson, *North Carolina State University*Phyliss Salmons, *Embry—Riddle Aeronautical University* 

Michael Schaab, Maine Maritime Academy

Bruce Schumm, *University of California, Santa Cruz* Mizuho Schwalm, *University of Minnesota Crookston* 

Cindy Schwarz, Vassar College

Natalia Semushkhina, *Shippensburg University* Khazhgery (Jerry) Shakov, *Tulane University* 

Kathy Shan, University of Toledo

Anwar Sheikh, Colorado Mesa University Bart Sheinberg, Houston Community College

Marllin Simon, Auburn University

Kenneth Smith, *Pennsylvania State University* Michael Smutko, *Northwestern University* 

Jon Son, Boston University

Noel Stanton, Kansas State University
Donna Stokes, University of Houston
Chuck Stone, North Carolina A&T
Chun Fu Su, Mississippi State University
Jeffrey Sudol, West Chester University
Scott Thompson, Georgia Gwinnett College
William Tireman, Northern Michigan University
Negussie Tirfessa, Manchester Community College

Rajive Tiwari, *Belmont Abbey College*Herman Trivilino, *College of the Mainland*Dmitri Tsybychev, *Stony Brook University*Douglas Tussey, *Pennsylvania State University*Stephen Van Hook, *Pennsylvania State University* 

Manuel Valera, Slippery Rocky University Christos Valiotis, Antelope Valley College James Vesenka, University of New England Stamatis Vokos, Seattle Pacific University

James Wanliss, Embry—Riddle Aeronautical University

Henry Weigel, Arapahoe Community College Luc T. Wille, Florida Atlantic University

Courtney Willis, University of Northern Colorado

Katherine Wu, University of Tampa

Ali Yazdi, Jefferson State Community College David Young, Louisiana State University Hsiao-Ling Zhou, Georgia State University Todd Zimmerman, University of Wisconsin—Stout Ulrich Zurcher, Cleveland State University

### **About the Cover**

The cover image isn't just a pretty picture. All of the elements—the lensing by the water droplet, the structure of the feather, the mechanism for the feather colors—make an appearance as applications of the physics concepts that students are learning.

# Preface to the Student

One may say the eternal mystery of the world is its comprehensibility.

—Albert Einstein

If you are taking a course for which this book is assigned, you probably aren't a physics major or an engineering major. It's likely that you aren't majoring in a physical science. So why are you taking physics?

It's almost certain that you are taking physics because you are majoring in a discipline that requires it. Someone, somewhere, has decided that it's important for you to take this course. And they are right. There is a lot you can learn from physics, even if you don't plan to be a physicist. We regularly hear from doctors, physical therapists, biologists, and others that physics was one of the most interesting and valuable courses they took in college.

So, what can you expect to learn in this course? Let's start by talking about what physics is. Physics is a way of thinking about the physical aspects of nature. Physics is not about "facts." It's far more focused on discovering *relationships* between facts and the *patterns* that exist in nature than on learning facts for their own sake. Our emphasis will be on thinking and reasoning. We are going to look for patterns and relationships in nature, develop the logic that relates different ideas, and search for the reasons *why* things happen as they do.



The concepts and techniques you will learn will have a wide application. In this text we have a special emphasis on applying physics to understanding the living world. You'll use your understanding of charges and electric potential to analyze the electrical signal produced when your heart beats. You'll learn how sharks can

detect this signal to locate prey and, further, how and why this electrical sensitivity seems to allow hammerhead sharks to detect magnetic fields, aiding navigation in the open ocean.

Like any subject, physics is best learned by doing. "Doing physics" in this course means solving problems, applying what you have learned to answer questions at the end of the chapter. When you are given a homework assignment, you may find yourself tempted to simply solve the problems by

thumbing through the text looking for a formula that seems like it will work. This isn't how to do physics; if it was, whoever required you to take this course wouldn't bother. The folks who designed your major want you to learn to *reason*, not to "plug and chug." Whatever you end up studying or doing for a career, this ability will serve you well.

How do you learn to reason in this way? There's no single strategy for studying physics that will work for all students, but we can make some suggestions that will certainly help:

- Read each chapter *before* it is discussed in class. Class attendance is much more effective if you have prepared.
- Use the other resources that accompany the text. The text includes many videos and online tools to help you better master new material.
- Participate actively in class. Take notes, ask and answer questions, take part in discussion groups. There is ample scientific evidence that active participation is far more effective for learning science than is passive listening.
- After class, go back for a careful rereading of the chapter. In your second reading, pay close attention to the details and the worked examples. Look for the *logic* behind each example, not just at what formula is being used.
- Apply what you have learned to the homework problems at the end of each chapter. By following the techniques of the worked examples, applying the tactics and problem-solving strategies, you'll learn how to apply the knowledge you are gaining.
- Form a study group with two or three classmates. There's good evidence that students who study regularly with a group do better than the rugged individualists who try to go it alone.
- Don't be afraid to ask questions. The more you engage with your instructor and other students, the more successful you will be.

We have one final suggestion. As you read the book, take part in class, and work through problems, step back every now and then to appreciate the big picture. You are going to study topics that range from motions in the solar system to the electrical signals in the nervous system that let you tell your hand to turn the pages of this book. It's a remarkable breadth of topics and techniques that is based on a very compact set of organizing principles.

Now, let's get down to work.

# Studying for and Taking the MCAT Exam

If you are taking the College Physics course, there's a good chance that you are majoring in the biological sciences. There's also a good chance that you are preparing for a career in the health professions, and so might well be required to take the Medical College Admission Test, the MCAT exam.

The Chemical and Physical Foundations of Biological Systems section of the MCAT assesses your understanding of the concepts of this course by testing your ability to apply these concepts to living systems. You will be expected to use what you've learned to analyze situations you've never seen before, making simplified but realistic models of the world. Your reasoning skills will be just as important as your understanding of the universal laws of physics.

### Structure of the MCAT Exam

Most of the test consists of a series of passages of technical information followed by a series of questions based on each passage, much like the passage problems at the end of each chapter in this book. Some details:

- The passages and the questions are always integrated. Understanding the passage and answering the questions will require you to use knowledge from several different areas of physics.
- Passages will generally be about topics for which you do not have detailed knowledge. But, if you read carefully, you'll see that the treatment of the passage is based on information you should know well.
- The test assumes a basic level of background knowledge. You'll need to have facility with central themes and major concepts, but you won't need detailed knowledge of any particular topic. Such detailed information, if needed, will be provided in the passage.
- You can't use calculators on the test, so any math that you do will be reasonably simple. Quickly estimating an answer with ratio reasoning or a knowledge of the scale of physical quantities will be a useful skill.
- The answers to the questions are all designed to be plausible. You can't generally weed out the "bad" answers with a quick inspection.
- The test is given online. Practicing with Mastering Physics will help you get used to this format.

### **Preparing for the Test**

Because you have used this book as a tool for learning physics, you should use it as a tool for reviewing for the MCAT

exam. Several of the key features of the book will be useful for this, including some that were explicitly designed with the MCAT exam in mind.

As you review the chapters:

- Start with the Chapter Previews, which provide a "big picture" overview of the content. What are the major themes of each chapter?
- Look for the Synthesis boxes that bring together key concepts and equations. These show connections and highlight differences that you should understand and be ready to apply.
- Go through each chapter and review the Stop to Think exercises. These are a good way to test your understanding of the key concepts and techniques.
- Each chapter closes with a passage problem that is designed to be "MCAT-exam-like." They'll give you good practice with the "read a passage, answer questions" structure of the MCAT exam.

The passage problems are a good tool, but the passages usually don't integrate topics that span several chapters—a key feature of the MCAT exam. For integrated passages and problems, turn to the *Part Summaries:* 

- For each Part Summary, read the *One Step Beyond* passage and answer the associated questions.
- After this, read the passages and answer the questions that end each Part Summary section. These passages and associated problems are—by design—very similar to the passages and questions you'll see on the actual MCAT exam.

### Taking the Test: Reading the Passage

As you read each passage, you'll need to interpret the information presented and connect it with concepts you are familiar with, translating it into a form that makes sense based on your background.

The next page shows a passage that was written to very closely match the style and substance of an actual MCAT passage. Blue annotations highlight connections you should make as you read. The passage describes a situation (the mechanics and energetics of sled dogs) that you probably haven't seen before. But the basic physics (friction, energy conversion) are principles that you are familiar with, principles that you have seen applied to related situations. When you read the passage, think about the underlying physics concepts and how they apply to this case.

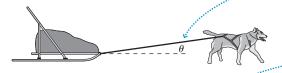
### **Translating the Passage**

As you read the passage, do some translation. Connect the scenario to examples you've seen before, translate given information into forms you are familiar with, think about the basic physical principles that apply.

### Passage X

For travel over snow, a sled with runners that slide on snow is the best way to get around. Snow is slippery, but there is still friction between runners and the ground; the forward force required to pull a sled at a constant speed might be 1/6 of the sled's weight.

The pulling force might well come from a dog. In a typical sled, the rope that the dog uses to pull attaches at a slight angle, as in Figure 1. The pulling force is the horizontal component of the tension in the rope.



### Figure 1

Sled dogs have great aerobic capacity; a 40 kg dog can provide output power to pull with a 60 N force at 2.2 m/s for hours. The output power is related to force and velocity by  $P = F \cdot v$ , so they can pull lighter loads at higher speeds.

Doing 100 J of work means that a dog must expend 400 J of metabolic energy. The difference must be exhausted as heat; given the excellent insulation provided by a dog's fur, this is mostly via evaporation as it pants. At a typical body temperature, the evaporation of 1.0 l of water carries away 240,000 J, so this is an effective means of cooling.

-- As you read this part of the passage, think about the forces involved: For a sled moving at a constant speed, there is no net force. The downward weight force is equal to the upward normal force; the forward pulling force must be equal to the friction force, which is acting opposite the sled's motion. There are many problems like this in Chapter 5.

Part of translating is converting given information into a more usual or more useful form. This is really a statement about the coefficient of kinetic friction.

The force applied to the sled is the tension force in the rope, which is shown at an angle. The horizontal component is the pulling force; you're told this. There is a vertical component of the force as well.

···· In the data given here, and the description given above, the sled moves at a constant speed—there is no mention of acceleration anywhere in this passage. In such cases, the net force is zero and the kinetic energy of the sled isn't changing.

Notice that the key equation relating power, force, and velocity is given to you. That's to be expected. Any specific information, including equations, constants, and other such details, will generally be given in the passage. The MCAT is a test of reasoning, not recall.

The concepts of metabolic energy and energy output are treated in Chapter 11. The details here match those in the chapter (as they should!); this corresponds to an efficiency of 25%. 400 J of energy is used by the body; 25% of this, 100 J, is the energy output. This means that 300 J is exhausted as heat.

Chapter 12 discusses means of heat transfer: conduction, convection, radiation, evaporation. This paragraph gives biological details about dogs that you can interpret as follows: A dog's fur limits transfer by conduction, convection, and radiation; evaporation of water by a panting dog must take up the slack.

The specific data for energy required to evaporate water are given. If you need such information to answer questions, it will almost certainly be provided. As we noted above, this is a test of reasoning, not recall.

### Taking the Test: Answering the Questions

The passages on the MCAT exam seem complicated at first, but, as we've seen, they are about basic concepts and central themes that you know well. The same is true of the questions; they aren't as difficult as they may seem at first. As with the passage, you should start by translating the questions, identifying the physical concepts that apply in each case. You then proceed by reasoning, determining the solution to the question, using your understanding of these basic concepts. The practical suggestions below are followed by a detailed overview of the solutions to the questions based on the passage on the previous page.

### You Can Answer the Questions in Any Order

The questions test a range of skills and have a range of difficulties. Many questions will involve simple reading comprehension; these are usually quite straightforward. Some require sophisticated reasoning and (slightly) complex mathematical manipulations. Start with the easy ones, ones that you can quickly solve. Save the more complex ones for later, and skip them if time is short.

## Take Steps to Simplify or Eliminate Calculations

You won't be allowed to use a calculator on the exam, so any math that you do will be reasonably straightforward. To rapidly converge on a correct answer choice, there are some important "shortcuts" that you can take.

Use ratio reasoning. What's the relationship between the variables involved in a question? You can use this to deduce the answer with only a very simple calculation, as we've seen many times in the book. For instance, suppose you are asked the following question:

A model rocket is powered by chemical fuel. A student launches a rocket with a small engine containing 1.0 g of combustible fuel. The rocket reaches a speed of 10 m/s. The student then launches the rocket again, using an engine with 4.0 g of fuel. If all other parameters of the launch are kept the same, what final speed would you expect for this second trial?

This is an energy conversion problem: Chemical energy of the fuel is converted to kinetic energy of the rocket. Kinetic energy is related to the speed by  $K = \frac{1}{2}mv^2$ . The chemical energy—and thus the kinetic energy—in the second trial is increased by a factor of 4. Since  $K \sim v^2$ , the speed must increase by a factor of 2, to 20 m/s.

Simplify calculations by liberally rounding numbers. You can round off numbers to make calculations more straightforward. Your final result will probably be close enough to choose the correct answer from the list given. For instance, suppose you are asked the following question:

A ball moving at 2.0 m/s rolls off the edge of a table that's 1.2 m high. How far from the edge of the table does the ball land?

A. 2 m B. 1.5 m C. 1 m D. 0.5 m

We know that the vertical motion of the ball is free fall; so the vertical distance fallen by the ball in a time  $\Delta t$  is  $\Delta y = -\frac{1}{2}gt^2$ . The time to fall 1.2 m is  $\Delta t = \sqrt{2(1.2 \text{ m})/g}$ . Rather than complete this calculation, we estimate the results as follows:  $\Delta t = \sqrt{2.4/9.8} \approx \sqrt{1/4} = 1/2 = 0.5 \text{s}$ . During this free-fall time, the horizontal motion is constant at 2.0 m/s, so we expect the ball to land about 1 m away. Our quick calculation shows us that the correct answer is choice C—no other answer is close.

- For calculations using values in scientific notation, compute either the first digits or the exponents, not both. In some cases, a quick calculation can tell you the correct leading digit, and that's all you need to figure out the correct answer. In other cases, you'll find possible answers with the same leading digit but very different exponents or decimal places. In this case, all you need is a simple order-of-magnitude estimate to decide on the right result.
- Where possible, use your knowledge of the expected scale of physical quantities to quickly determine the correct answer. For instance, suppose a question asks you to find the photon energy for green light of wavelength 550 nm. Visible light has photon energies of about 2 eV, or about 3 × 10<sup>-19</sup> J, and that might be enough information to allow you to pick out the correct answer with no calculation.
- Beware of "distractors," answers that you'll get if you make common mistakes. For example, Question 4 on the next page is about energy conversion. The dog is keeping the sled in motion, so it's common for students to say that the dog is converting chemical energy in its body into kinetic energy. However, the kinetic energy isn't changing. The two answer choices that involve kinetic energy are common, but incorrect, choices. Be aware that the questions are constructed to bring out such misconceptions and that these tempting, but wrong, answer choices will be provided.

### One Final Tip: Look at the Big Picture

The MCAT exam tests your ability to look at a technical passage about which you have some background knowledge and quickly get a sense of what it is saying, enough to answer questions about it. Keep this big picture in mind:

- Don't get bogged down in technical details of the particular situation. Focus on the basic physics.
- Don't spend too much time on any one question. If one question is taking too much time, make an educated guess and move on.
- **Don't get confused by details of notation or terminology.** For instance, different people use different symbols for physical variables. In this text, we use the symbol K for kinetic energy; others use  $E_K$ .

Finally, don't forget the most important aspect of success on the MCAT exam: The best way to prepare for this or any test is simply to understand the subject. As you prepare for the test, focus your energy on reviewing and refining your knowledge of central topics and techniques, and practice applying your knowledge by solving problems like you'll see on the actual MCAT.

### **Translating**

Look at the questions and think about the physics principles that apply, how they connect to concepts you know and understand.

This is a question about the size of ... the friction force. You are told that it takes a force that's about 1/6 of the sled's weight to pull it forward on snow. You can estimate the friction coefficient from this information.

If the speed is constant, there is no met force. We are told that the pulling force is the horizontal component of the tension force, not the tension force itself. Because there is no net force, this horizontal component is equal to the friction force, which is directed backward. So this is really a question about the friction force.

We assume that the output ...... power is the same for the two cases—this is implied in the passage.

This is a question about energy.... transformation. For such questions, think about changes. What forms of energy are *changing?* We know that thermal energy is part of the picture because some of the chemical energy is converted to thermal energy in the dog's body.

Increasing speed increases power,  $\cdot \cdot$  as the passage told us. But the energy to pull the sled is not the *power*, it's the *work*, and we know that the work is  $W = F\Delta x$ . This is a question about work and energy, not about power.

The passage tells us that the dog uses 400 J of metabolic energy to do 100 J of work. 300 J, or 75%, must be exhausted to the environment. We can assume the same efficiency here.

### **Tips**

- Numerical choices are presented in order; that's the usual practice on the test. Estimate the size of the answer, and think about where it falls.
- For questions with sentences as choices, decide on the solution before you look at the choices; this will save time reading.
- 1. What is the approximate coefficient of kinetic
- ···· friction for a sled on snow?

A. 0.35

B. 0.25

C. 0.15

D. 0.05

- 2. If a rope pulls at an angle, as in Figure 1, how will this affect the pulling force necessary to keep the sled moving at a constant speed?
  - A. This will reduce the pulling force.
  - B. This will not change the pulling force.
  - C. This will increase the pulling force.
  - D. It will increase or decrease the pulling force, depending on angle.
- **3.** A dog pulls a 40 kg sled at a maximum speed of 2 m/s. What is the maximum speed for an 80 kg sled?

A. 2 m/s

B. 1.5 m/s

C. 1.0 m/s .....

D. 0.5 m/s

- This is a question about energy.

  4. As a dog pulls a sled at constant speed, transformation. For such chemical energy in the dog's body is converted to
  - A. kinetic energy
  - B. thermal energy 4
  - C. kinetic energy and thermal energy
  - D. kinetic energy and potential energy
  - 5. A dog pulls a sled for a distance of 1.0 km at a speed of 1 m/s, requiring an energy output of 60,000 J. If the dog pulls the sled at 2 m/s, the necessary energy is

A. 240,000 J

B. 120,000 J

C. 60,000 J ....

D. 30,000 J

**6.** A dog uses 100,000 J of metabolic energy pulling a sled. How much energy must the dog exhaust by panting?

A. 100,000 J

B. 75,000 J 4...

C. 50,000 J

D. 25,000 J

### Reasoning

Think about the question and the range of possible answers, and converge to a solution with as few steps as possible—time is limited!

For an object on level ground, the normal force equals the weight force. If the sled is moving at a constant speed, the pulling force equals the friction force. This implies that  $\mu = f_k / n = f_{pull} / w = 1/6$ . Two of the answer choices convert easily to fractions: 0.25 = 1/4; 0.05 = 1/20. 1/6 is between these, so C must be our choice. (Indeed, 1/6 = 0.167, so 0.15 is pretty close.)

A vertical component of the tension force will reduce the normal force, reducing the friction force—and thus the pulling force.

Doubling the weight doubles the normal force, which doubles the friction force. This will double the necessary pulling force as well. Given the expression for power given in the passage, this means the maximum speed will be halved.

• Choice B is correct, but A and C are clever distractors. It's tempting to choose an answer that includes kinetic energy. The sled is in motion, after all! But don't be swayed. The kinetic energy isn't changing, and friction to the sled converts any energy the dog supplies into thermal energy.

Doubling the speed doubles the power, but it doesn't change the force; that's fixed by friction. The distance is the same as well, and so is the work done, the energy required. Since the speed doubles, it's tempting to think the energy doubles, though. This "obvious" but incorrect solution is one of the choices—expect such situations on the actual MCAT.

"... If 75% of the energy must be exhausted to the environment, that's 75,000 J.

# Real-World Applications

Applications of biological or medical interest are marked [80] in the list below, including MCAT-style Passage Problems. Other end-of-chapter problems of biological or medical interest are marked [80] in the chapter.

### **Chapter 1**

Depth gauges 8
Accuracy of long jumps 14
Mars Climate Orbiter: unit error 16

80 Navigating geese 24

### **Chapter 2**

Crash cushions 44

- 80 Animal acceleration 44 Rocket launch 47–48, 53
- **BIO** Swan's takeoff 50
- Chameleon tongues 52 Runway design 54 Braking distance 55
- **BO** A springbok's pronk 58
- (B) Cheetah vs. gazelle 60

### **Chapter 3**

Designing speed-ski slopes 80 Dock jumping 87 London Eye Ferris wheel 90 Optimizing javelin throws 93

- Albatross's speed 93
- Record-breaking frog jumps 95

### Chapter 4

- Snake-necked turtle attack 105, 124 Voyager and Newton's first law 106 Seatbelts and Newton's first law 107
- Prosthetics for athletes 110 Scallop propulsion 113

Feel the difference (inertia) 117
Race-car driver mass 118
Bullets and Newton's third law 123
Rocket propulsion 124
A mountain railway 125

Pulling a stuck car from the mud 133

### **Chapter 5**

- Gliding sifaka 125, 154
  Human tower 135
  Jumping on the moon 141
  Jumping in an elevator 142
  Weightless astronauts 144
  Antilock brakes 148
- Penguin drag coefficient 153
  Skydiver terminal speed 153–154
- 80 Mass of a pollen grain 155
- **BO** Paramecium stopping distance 156
- Traction 161
  Stopping distances 164

### **Chapter 6**

Scottish heavy hammer throw 178
Runner on a circular track 180–181
Car cornering speed 181–182
Wings on Indy racers 182

Banked racetrack turns 183

- Maximum walking speed 168
  How you sense "up" 185
  Fast-spinning planets 186
- Centrifuges 186–187
- BO Human centrifuge 187
- Rotating space stations 189
  Variable gravity 192
- Walking on the moon 193 Hunting with a sling 195–196

### **Chapter 7**

Clockwise clocks 211
Starting a bike 216
Designing wheelchair
hand-rims 216
Turning a capstan 218
Granite ball and inertia 224
Golf putter moment of inertia 225
Balancing on a high wire 226
Rolling vs. sliding: ancient
movers 231
Spinning a gyroscope 232–233

BIO Bunchberry petal release 242

### **Chapter 8**

- BIO Human stability and balance 244, 251
- BIO Muscle forces 245
- Finding the body's center of gravity 249

  Rollover safety for cars 250

  Ladder safety 251

  Balancing soda can 251

  Elasticity of a golf ball 252
- Blo Bone strength 257–258
- BO Forces in the ankle joint 259–260

Running shoes and springs 253

- Forces and torque in the elbow 260–261
- Carrying a heavy appliance 261 Elevator cable stretch 262
- **BIO** Elasticity of a Ligament

### **Part I Summary**

Dark matter 276

BIO Animal athletes 277

- BIO Drag on a paramecium 277
- BIO Diving falcon 278
  Bending beams 278

### **Chapter 9**

- **BO** Ram skull adaptations 278, 284
- Optimizing frog jumps 281 Stretchy seatbelts 284
- BO Hedgehog spines 284
- Birds taking flight 286–287
- Squid propulsion 292
  Colliding billiard balls 288
  Ice-skating spins 297
  Hurricanes 298
  Free-falling geckos 298
  Acrobatic bats 298
  Aerial firefighting 299
- BIO Analyzing a dance move 308

### **Chapter 10**

Energy around us 318–319 Flywheel energy storage on the ISS 328

Why racing bike wheels are light 328–329

Empire State Building race 330-331

- Energy storage in the Achilles tendon 332
- Jumping locusts 336–337
  Summet Plummet water slide
  speed 337
  Runaway-truck ramps 352

### **Chapter 11**

- Kangaroo locomotion 354, 390 Lightbulb efficiency 357
- Biochemical efficiency 358
- Blo Energy in the body: inputs 358–359
- **Blo** Calorie content of foods 359
- Blo Energy in the body: outputs 359–360
- Daily energy use for mammals and reptiles 361
- Energy and locomotion 363
  Optical molasses 365
  Heat engines 370
  Reversible heat pump 373
- Entropy in biological systems 378–379
  Efficiency of an automobile 380–381
- BIO Animal power 389

### **Part II Summary**

Order out of chaos 391

BIO Squid propulsion 393 Golf club collisions 393

### **Chapter 12**

- Infrared images 396, 426, 431 Temperature in space 400 Frost on Mars 401
- Swim-bladder damage to caught fish 403

Tire gauges 404 Elevation and bag expansion 408 Chinook winds 411 Thermal expansion joints 412

Temperate lakes 414

Blo Frogs that survive freezing 416

Keeping cool 418
Sweating glass 418

BO Penguin feet 424

Penguin feathers 424
Heat transfer on earth 425

BIO Hellbender respiration 429

- Photosynthesis and carbon dioxide diffusion 429
- Breathing in cold air 430 Ocean temperature 440
- BIO The work of breathing 440

BO Albatross and Bernoulli

### **Chapter 13**

effect, 441, 458
Submarine windows 445
Pressure zones on weather maps 447
Barometers 447
Floating icebergs and boats 451
Hot-air balloons 452–453
Manatees: masters of density 453

Airplane lift 458

Prairie dog burrows 459

(BIO) Measuring arterial pressure 460

Measuring blood pressure 463

Blood pressure in giraffes 465

Blood pressure and flow 465–466, 477

BO Capillaries and diffusion 466

Horse hooves and circulation 468

Intravenous transfusions 468–469

### **Part III Summary**

**BO** Scales of living creatures 479

Perspiration 480
Weather balloons 480
Passenger balloons 481

### **Chapter 14**

- Bio Gibbon brachiation 484, 502
- Blo Heart rhythms 485
- Simple harmonic motion 486 Metronomes 490 Microwaves and SHM 493

Swaying buildings 493 Measuring mass in space 496

- Weighing DNA 497–498
  Car collision times 499
- Animal locomotion 502 Shock absorbers 503 Tidal resonance 504 Musical glasses 505
- BO Hearing (resonance) 506 Springboard diving 507–508
- BIO Achilles tendon as a spring 517
- BIO Spider-web oscillations 517

### **Chapter 15**

- Echolocation 518, 529, 548 "The Wave" 519
- **BIO** Frog wave-sensors 521
- Spider vibration sense 522
  Distance to a lightning strike 523
- Range of hearing 529
- **BIO** Ultrasound imaging 530
- BO Owl ears 533
- Blue whale vocalization 534
- Hearing (cochlea hairs) 535 Solar surface waves 536 Red shifts in astronomy 538
- Wildlife tracking with weather radar 538
- BO Doppler blood flow meter 539
  Earthquake waves 540

### **Chapter 16**

Digdgeridoos 549, 558, 564 Windows and transmitting light 554 The Tacoma bridge standing wave 557 String musical instruments 557

Microwave cold spots 558
Fiery sound waves 560

- Resonances of the ear canal 561–562
  Wind musical instruments 562
- **BO** Speech and hearing 563–565
- Wowels and formants 564 Saying "ah" 565
- High-frequency hearing loss 565 Active noise reduction 565 Controlling exhaust noise 569
- Rio The bat detector 570
- BO Dogs' growls 571 Harmonics and harmony 579

### **Part IV Summary**

Tsunamis 581
Deep-water waves 582

BIO Attenuation of ultrasound 582 Measuring speed of sound 583

### **Chapter 17**

Iridescent feathers 586, 603 DVD colors 597 Antireflection coatings 601 Colors of soap bubbles and oil slicks 603

Peacock fern and structural color 603–604

Bluebirds and blue skies 605
Breakwaters and Huygens'
principle 606
Laser range finding 611

**Blo** The Blue Morpho Butterfly 619

### **Chapter 18**

Glass repair and index of refraction 628 Binoculars 630 Snell's window 630 Optical fibers 631

- 80 Arthroscopic surgery 631
- Water droplet as converging lens 638
- Mirrored eyes (Gigantocypris) 641 Supermarket mirrors 643
- Optical fiber imaging 647–648 Mirages 656

### **Chapter 19**

- The Anableps "four-eyed" fish 657, 667
- BO A Nautilus eye 658 Cameras 658–660
- The human eye 660–667 Prescription lenses 660
- Bio Eye's range of accommodation, 663
- 80 Vision correction 664, 665–667
- Penguin eyes 667
  Forced perspective in movies 668
- Microscopes 670–673, 681
  Telescopes above the
  atmosphere 673
  Rainbows 676
- Absorption of chlorophyll 677 Fixing the HST 678
- Optical and electron micrographs 680
- 80 Visual acuity for a kestrel 682
- BIO The blind spot 685
- **BIO** Surgical vision correction 689

### **Part V Summary**

- **BO** Scanning confocal microscopy 691
- BIO Horse vision 692
- BIO Eye shine 692–693
- BIO Pupil size 693

### **Chapter 20**

Bee navigation 696, 711
Amber attraction 697
Dust in the wind 699
Static electricity on a slide 700

Booking up pollen 702

**BO** Hydrogen bonds in DNA 705

- **BO** Separating sperm cells 706 Electrostatic precipitators 715–716
- BIO Electric field of the heart 718 Static protection 720 Lightning rods 720
- **BO** Electrolocation 720 Cathode-ray tubes 723-724
- BIO Flow cytometry 733

### **Chapter 21**

- Blo Rays and electric potential 734, 757 Cause of lightning 738, 773
- **BO** Membrane potential 739
- BIO Proton therapy 743
- BIO Bumblebee electric-field sensitivity 749 Airplanes and lightning strikes 754
- BO The electrocardiogram 755–756
- BIO Shark electroreceptors 757
- Random-access memory 759 BIO Plant roots and capacitance 761 Camera flashes 761
- BO Defibrillators 762 Fusion in the sun 764

### Chapter 22

- **80** Percentage body-fat measurement 774, 790-791
- BO The electric torpedo ray 780 Lightbulb filaments 783 Testing drinking water 784
- BIO Impedance tomography 784 Photoresistor night lights 785 Cooking hot dogs with electricity 788 Monitoring corrosion in power lines 789 Lightbulb failure 799

### **Chapter 23**

- **BIO** Electric fish 800, 837 Christmas-tree lights 807 Headlight wiring 809 Thermistors in measuring devices 811 Cell phone circuitry, 812 Flashing bike light 816 Intermittent windshield wipers 819
- Blo Electricity in the nervous system 819–825
- BIO Electrical nature of nerve and muscle cells 819
- BIO Interpreting brain electric potentials 822 Soil moisture measurement 826
- **BIO** Cardiac defibrillators 837

### Chapter 24

80 Magnetic resonance imaging 838, 850, 864

- BO Magnetotactic bacteria 843 Magnetocardiograms 849
  - Digital compass 853 The aurora 855
- BIO Cyclotrons 856
- Blo Electromagnetic flowmeters 857 Electric motors 864 Hard disk data storage 867 Rotating magnetic bacteria 868 The velocity selector 877 Ocean potentials 878 The mass spectrometer 878

### **Chapter 25**

- BO Color vision in animals 879, 903
- Shark navigation 882 Generators 883-884 Wind turbine 884 Electric guitar pickups 889 Magnetic braking 892
- BIO Transcranial magnetic stimulation 892 Radio transmission 894 Solar tower of power 895 Polarizers 896-898
- BIO Polarizers and blood-glucose tests 898
- **BO** Polarization analysis 897
- BO Honeybee navigation 898
- BO Wildlife tracking 901 Colors of glowing objects 901
- BO Infrared sensors in snakes 902
- BO Seeing (infra)red 903 Astronomical images 904 Tethered satellite circuits 905
- Electromagnetic wave penetration 915 Metal detectors 915

### **Chapter 26**

Transformers 919-921 Charging electric toothbrushes 921 Power transmission 922 Household wiring 923–925

- Electrical safety 925-927 The lightning crouch 927 GFI circuits 927, 936 Laptop trackpads 928 Under-pavement car detectors 930 Cleaning up computer power 931
- 80 Nuclear magnetic resonance 934
- Cell membrane capacitance 943 Halogen bulbs 943

### **Part VI Summary**

The greenhouse effect and global warming 945

BIO Taking x rays 946 Electric cars 947 Wireless power transmission 947

### **Chapter 27**

Global Positioning Systems 950, 960, 963, 976–977

The Stanford Linear Accelerator 968 Nuclear fission 976

BO Pion therapy 985

### **Chapter 28**

- Blo Electron microscopy 986
- **BO** X-ray imaging 987
- (BO) X-ray diffraction of DNA 989
- Biological effects of UV 992
- Frequencies for photosynthesis 993
- (BIO) Waves, photons, and vision 996
- BIO Transmission electron microscopes 999-1000 Scanning tunneling microscopy 1007
- Magnetic resonance imaging 1008-1009 Electron diffraction 1017-1018 Collisional excitation 1018

### Chapter 29

Spectroscopy 1020 Colors of nebulae 1021 Sodium filters for telescopes 1040

- Fluorescence 1041-1042
- BIO LASIK surgery 1044 Compact fluorescent lighting 1044-1045 Light-emitting diodes 1053

### Chapter 30

Body scans 1054

- Deuterium and tracking migrating birds 1056 Nuclear fusion in the sun 1059 Nuclear power 1060
  - Smoke detectors and sensing circuits 1063
- Beta decay in the human body 1065
- Food irradiation 1068
- Graves disease and radioactive iodine 1070 Plutonium "batteries" 1071
  - Radiocarbon dating 1072–1073
- Gamma-ray medical sterilization 1074 Radiation dose from environmental sources 1074
- 80 Nuclear medicine 1075–1076
- BIO Nuclear imaging, PET scans 1076-1078 Čerenkov radiation 1082
- BIO Plutonium-powered exploration 1089 Nuclear fission 1089

### **Part VII Summary**

Low-temperature physics 1091 Splitting the atom 1092

# **Detailed Contents**

Preface to the Instructor	iv	Chapter 3	<b>Vectors and Motion in Two</b>	
Preface to the Student	xii		Dimensions	71
Studying for and Taking the MCAT Exam	xiii	3.1	Using Vectors	72
Real-World Applications	xvii		Coordinate Systems and Vector	
			Components	74
77 175 41		3.3	Motion on a Ramp	79
PART I Force and Motion		3.4	Motion in Two Dimensions	82
overview The Science of Physics	3	3.5	Projectile Motion	85
•	_	3.6	Projectile Motion: Solving	
and the second s			Problems	87
2 7 d 1		3.7	Circular Motion	90
The state of the s		3.8	Relative Motion	93
			SUMMARY	96
A Photo de la			QUESTIONS AND PROBLEMS	97
S. S. F.		Chapter 4	Forces and Newton's Laws	
1-20-1		Chapter 4	of Motion	105
		4.1	Motion and Forces	106
			A Short Catalog of Forces	100
Chapter 1 Representing Motion	4		Identifying Forces	113
1.1 Motion: A First Look	_		What Do Forces Do?	115
1.1 Models A First Look 1.2 Models and Modeling	5 7		Newton's Second Law	117
1.3 Position and Time: Putting	/		Free-Body Diagrams	120
Numbers on Nature	8		Newton's Third Law	122
1.4 Velocity	11		SUMMARY	126
1.5 A Sense of Scale: Significant Figures,	11		QUESTIONS AND PROBLEMS	127
Scientific Notation, and Units	13			
1.6 Vectors and Motion: A First Look	19	Chapter 5	Applying Newton's Laws	134
<b>1.7</b> Where Do We Go from Here?	23	5.1	Equilibrium	135
SUMMARY	25	5.2	Dynamics and Newton's	
QUESTIONS AND PROBLEMS	26		Second Law	138
		5.3	Mass and Weight	141
Chapter 2 Motion in One Dimension	<b>32</b>	5.4	Normal Forces	144
2.1 Describing Motion	33	5.5	Friction	146
<b>2.2</b> Uniform Motion	37	5.6	Drag	151
2.3 Instantaneous Velocity	41		Interacting Objects	157
<b>2.4</b> Acceleration	44	5.8	Ropes and Pulleys	159
2.5 Motion with Constant Acceleration	47		SUMMARY	165
<b>2.6</b> Solving One-Dimensional Motion			QUESTIONS AND PROBLEMS	166
Problems	51			
<b>2.7</b> Free Fall	55			
SUMMARY	61			
QUESTIONS AND PROBLEMS	62			

**QUESTIONS AND PROBLEMS** 



Chapter 6	Circular Motion, Orbits,			
	and Gravity	175		
6.1	Uniform Circular Motion	176		
6.2	Dynamics of Uniform Circular			
	Motion	178		
6.3	Apparent Forces in Circular Motion	184		
6.4	Circular Orbits and Weightlessness	187		
6.5	Newton's Law of Gravity	190		
6.6	Gravity and Orbits	193		
	SUMMARY	197		
	QUESTIONS AND PROBLEMS	198		
Chapter 7	<b>Rotational Motion</b>	205		
7.1	Describing Circular and Rotational			
	Motion	206		
7.2	The Rotation of a Rigid Body	211		
	Torque	215		
7.4	Gravitational Torque and the			
	Center of Gravity	219		
7.5	Rotational Dynamics and			
	Moment of Inertia	223		
7.6	Using Newton's Second Law			
	for Rotation	227		
7.7	Rolling Motion	231		
	SUMMARY	234		
	QUESTIONS AND PROBLEMS	235		
Chapter 8	Equilibrium And Elasticity	244		
8.1	Torque and Static Equilibrium	245		
8.2		250		
8.3	•	252		
8.4	Stretching and Compressing			
	Materials	255		
8.5	Forces and Torques in the Body	258		
	SUMMARY	263		
	QUESTIONS AND PROBLEMS	264		
PART I SUMMAR		272		
ONE STEP BEYOND Dark Matter and the Structure				
	of the Universe	273		
PART I PROBLEM	18	274		

### PART II Conservation Laws

**OVERVIEW** Why Some Things Stay the Same 277



Chapter 9	Momentum	278
9.1	Impulse	279
9.2	Momentum and the	
	Impulse-Momentum Theorem	280
9.3	Solving Impulse and Momentum	
	Problems	285
9.4	Conservation of Momentum	287
9.5	Inelastic Collisions	292
9.6	Momentum and Collisions in Two	
	Dimensions	294
9.7	Angular Momentum	295
	SUMMARY	300
	QUESTIONS AND PROBLEMS	301
01 . 10	Enguerra and March	200
	Energy and Work	309
	The Basic Energy Model	310
	Work	314
	Kinetic Energy	318
	Potential Energy	321
	Thermal Energy	325
	Conservation of Energy	327
	Energy Diagrams	331
10.8	Molecular Bonds and Chemical	
	Energy	335
10.9	Energy in Collisions	339
10.10	Power	341
	SUMMARY	345
	QUESTIONS AND PROBLEMS	346

xxii	Detai	iled Contents			
Chapte	er <b>11</b>	Using Energy	354	Chapter 13 Fluids 4	141
	11.1	Transforming Energy	355	13.1 Fluids and Density	442
	11.2	Energy in the Body	358	13.2 Pressure	443
	11.3	Temperature, Thermal Energy,		13.3 Buoyancy	448
		and Heat	364	<b>13.4</b> Fluids in Motion	454
	11.4	The First Law of Thermodynamics	367	13.5 Fluid Dynamics	457
	11.5	Heat Engines	369	<b>13.6</b> Viscosity and Poiseuille's Equation	461
		Heat Pumps	372	J J	463
	11.7	Entropy and the Second Law		SUMMARY	470
		of Thermodynamics	374	QUESTIONS AND PROBLEMS	471
	11.8	Systems, Energy, and Entropy	377		
		SUMMARY	382	1	478
		QUESTIONS AND PROBLEMS	383		479
			200	PART III PROBLEMS	480
		RY Conservation Laws	390		
		OND Order Out of Chaos	391 392	PART IV Oscillations and Waves	
PART II P	ROBLE	MS	392	OSCILLATIONS AND WAVES	
		D CAR C		overview Motion That Repeats Again and Again	483
PAR	T III	Properties of Matter		and Again	+03
OVE	RVIEW	Beyond the Particle Model	395		
		1 M		Chapter 14 OSCILLATIONS 4	184
		The second secon		<b>14.1</b> Equilibrium and Oscillation	485
		The second second		<b>14.2</b> Linear Restoring Forces and SHM	487
N.				$\mathcal{C}$ 1	489
					494
					499
OI -	10	The sum of Duese suffers of Matter	206	*	502
Chapte		Thermal Properties of Matter	396		504
		The Atomic Model of Matter	397		509
	12.2	The Atomic Model of an Ideal Gas	399	QUESTIONS AND PROBLEMS	510

Chapter 15 Traveling Waves and Sound

**15.3** Graphical and Mathematical Descriptions of Waves

**15.4** Sound and Light Waves

**15.7** The Doppler Effect and Shock Waves

**QUESTIONS AND PROBLEMS** 

**15.5** Energy and Intensity

**15.6** Loudness of Sound

SUMMARY

**15.1** The Wave Model

**15.2** Traveling Waves

**518** 

519

520

524

529

531

533

536541

542

Chapter 12	Thermal Properties of Matter	396
12.1	The Atomic Model of Matter	397
12.2	The Atomic Model of an Ideal Gas	399
12.3	Ideal-Gas Processes	406
12.4	Thermal Expansion	412
12.5	Specific Heat and Heat	
	of Transformation	414
12.6	Calorimetry	418
12.7	Specific Heats of Gases	421
12.8	Heat Transfer	422
12.9	Diffusion	426
	SUMMARY	431
	QUESTIONS AND PROBLEMS	432

				Detailed Contents	xxiii
Chapter 16	Superposition and Standing		18.5	Thin Lenses: Ray Tracing	633
	Waves	<b>549</b>		Image Formation with Spherical	
16.1	The Principle of Superposition	550		Mirrors	639
	Standing Waves	551	18.7	The Thin-Lens Equation	644
	Standing Waves on a String	553		SUMMARY	649
	Standing Sound Waves	558		QUESTIONS AND PROBLEMS	650
	Speech and Hearing	563			
	The Interference of Waves from	202	Chapter 19	Optical Instruments	657
	Two Sources	565		=	
16.7	Beats	569		The Camera	658
	SUMMARY	572		The Human Eye	660
	QUESTIONS AND PROBLEMS	573		The Magnifier	667
				The Microscope	670
PART IV SUMMA	ARY Oscillations and Waves	580		The Telescope	673
	ND Waves in the Earth and the			Color and Dispersion	674
	Ocean	581	19.7	Resolution of Optical Instruments	677
PART IV PROBLE		582		SUMMARY	683
		002		QUESTIONS AND PROBLEMS	684
PART V	Optics		PART V SUMMA	_	690
ranı v	Optics		ONE STEP BEYO	ND Scanning Confocal Microscopy	691
OVERVIEW	Light Is a Wave	585	PART V PROBLEI	MS	692
	_				
25		2	PART VI	Electricity and Magneti	ism
		•	OVERVIEW	Charges, Currents, and Fields	695
		7		-	
4.5			Chapter 20	<b>Electric Fields and Forces</b>	696
	AG DE		20.1	Charges and Forces	697
100		•		Charges, Atoms, and Molecules	703
				Coulomb's Law	705
			20.4	The Concept of the Electric Field	710
				The Electric Field of Multiple	
				Charges	713
Chapter 17	Wave Optics	<b>586</b>	20.6	Conductors and Electric Fields	719
17.1	What Is Light?	587	20.7	Forces and Torques in Electric Fields	721
17.2	The Interference of Light	590		SUMMARY	725
	The Diffraction Grating	594		QUESTIONS AND PROBLEMS	726
	Thin-Film Interference	599			
17.5	Single-Slit Diffraction	605	Chapter 21	Electric Potential	734
	Circular-Aperture Diffraction	609			704
	SUMMARY	612	21.1	Electric Potential Energy and Electric Potential	725
	QUESTIONS AND PROBLEMS	613	24.2	Sources of Electric Potential	735 737
					131
Chapter 18	Ray Optics	620	21.3	Electric Potential and Conservation	740
	· -		24.4	of Energy Calculating the Floatric Potential	
	The Ray Model of Light	621		Calculating the Electric Potential	743 751
	Reflection Refrection	624		Connecting Potential and Field	755
	Refraction Image Formation by Refraction	627		The Electrocardiogram  Capacitance and Capacitors	757
18.4	Image Formation by Refraction	631		Capacitance and Capacitors Energy and Capacitors	761
			21.0	SUMMARY	765
				QUESTIONS AND PROBLEMS	766
				COLOTTORIO ATTO I HODELING	7 00

### xxiv



			25.1	Induced Currents	880
				Motional emf	881
			25.3	Magnetic Flux and Lenz's Law	884
Chapter 22	<b>Current and Resistance</b>	774		Faraday's Law	889
•	A Model of Current	775		Electromagnetic Waves	893
	Defining and Describing Current	777		The Photon Model of	
	Batteries and emf	779		Electromagnetic Waves	899
	Connecting Potential and Current	780	25.7	The Electromagnetic Spectrum	900
	Ohm's Law and Resistor Circuits	784		SUMMARY	906
	Energy and Power	788		QUESTIONS AND PROBLEMS	907
	SUMMARY	792			
	QUESTIONS AND PROBLEMS	793	Chapter 26	AC Electricity	916
			26.1	Alternating Current	917
Chapter 23	Circuits	800		AC Electricity and Transformers	919
	Circuit Elements and Diagrams	801	26.3	Household Electricity	923
	Kirchhoff's Laws	802	26.4	Biological Effects and	
	Series and Parallel Circuits	805		Electrical Safety	925
	Measuring Voltage and Current	810	26.5	Capacitor Circuits	927
	More Complex Circuits	811	26.6	Inductors and Inductor Circuits	929
	Capacitors in Parallel and Series	814	26.7	Oscillation Circuits	932
	RC Circuits	816		SUMMARY	937
23.8	Electricity in the Nervous System	819		QUESTIONS AND PROBLEMS	938
	SUMMARY	827			
	QUESTIONS AND PROBLEMS	828		RY Electricity and Magnetism	944
			ONE STEP BEYO	ND The Greenhouse Effect and	
Chapter 24	Magnetic Fields and Forces	838		Global Warming	945
	Magnetism	839	PART VI PROBLE	MS	946
	The Magnetic Field	840			
	Electric Currents Also Create	040			
24.5	Magnetic Fields	844			
24.4	Calculating the Magnetic Field	0-1-1			
24.4	Due to a Current	847			
24.5	Magnetic Fields Exert Forces	0.7			
	on Moving Charges	851			

**24.6** Magnetic Fields Exert Forces

**24.7** Magnetic Fields Exert Torques

**24.8** Magnets and Magnetic Materials

QUESTIONS AND PROBLEMS

Chapter 25 EM Induction and EM Waves

858

861 865

869

870

879

on Currents

on Dipoles

SUMMARY

1019

1020

1022

1025

1027

1032

1034

1037

1041

Chapter 29 Atoms and Molecules

**29.3** Bohr's Model of Atomic Quantization

**29.4** The Bohr Hydrogen Atom

29.5 The Quantum-Mechanical Hydrogen Atom

**29.7** Excited States and Spectra

**29.6** Multi-electron Atoms

**29.1** Spectroscopy

**29.2** Atoms

**29.8** Molecules

### PART VII Modern Physics

**OVERVIEW** New Ways of Looking at the World 949



			29.9	Stimulated Emission and Lasers	1042
Chapter 27	Relativity	950		SUMMARY	1046
27.1	Relativity: What's It All About?	951		QUESTIONS AND PROBLEMS	1047
27.2	Galilean Relativity	951			
27.3	Einstein's Principle of Relativity	954	Chapter 30	Nuclear Physics	1054
27.4	<b>Events and Measurements</b>	957	30.1	Nuclear Structure	1055
27.5	The Relativity of Simultaneity	960	30.2	Nuclear Stability	1057
27.6	Time Dilation	962		Forces and Energy in the Nucleus	1060
27.7	Length Contraction	968		Radiation and Radioactivity	1062
27.8	Velocities of Objects in			Nuclear Decay and Half-Lives	1068
	Special Relativity	970		Medical Applications of Nuclear	
	Relativistic Momentum	971		Physics	1073
27.10	Relativistic Energy	973	30.7	The Ultimate Building Blocks	
	SUMMARY	978		of Matter	1079
	QUESTIONS AND PROBLEMS	979		SUMMARY	1083
				QUESTIONS AND PROBLEMS	1084
Chapter 28	<b>Quantum Physics</b>	986			
28.1	X Rays and X-Ray Diffraction	987		RY Modern Physics	1090
28.2	The Photoelectric Effect	989	ONE STEP BEYON	The Physics of Very Cold Atoms	1091
28.3	Photons	995	PART VII PROBLE	MS	1092
28.4	Matter Waves	997			
28.5	Energy Is Quantized	1000		Mat. C. D.	A 1
28.6	Energy Levels and Quantum Jumps	1002		Mathematics Review	A-1
28.7	The Uncertainty Principle	1005		Periodic Table of Elements	A-3
28.8	Applications and Implications			Atomic and Nuclear Data	A-4
	of Quantum Theory	1007		dd-Numbered Problems	A-7
	SUMMARY	1010	Credits		C-1
	QUESTIONS AND PROBLEMS	1011	Index		I-1

# Force and Motion



### OVERVIEW



### The Science of Physics

Physics is the foundational science that underlies biology, chemistry, earth sciences, and all other fields that attempt to understand our natural world. Physicists couple careful experimentation with deep theoretical insights to build powerful and predictive models of how the world works. A key aspect of physics is that it is a *unifying* discipline: A relatively small number of key concepts can explain a vast array of natural phenomena. In this text, we have organized the chapters into parts according to seven of these unifying principles. Each of the seven parts of this text opens with an overview that gives you a look ahead, a glimpse of where your journey will take you in the next few chapters. It's easy to lose sight of the big picture while you're busy negotiating the terrain of each chapter. In Part I, the big picture is, in a word, *change*.

### Why Things Change

Simple observations of the world around you show that most things change. Some changes, such as aging, are biological. Others, such as the burning of gasoline in your car, are chemical. We will look at changes that involve *motion* of one form or another—running and jumping, throwing balls, lifting weights.

There are two big questions we must tackle to study how things change by moving:

- How do we describe motion? How should we measure or characterize the motion if we want to analyze it mathematically?
- How do we explain motion? Why do objects have the particular motion they do? Why, when you toss a ball upward, does it go up and then come back down rather than keep going up? What are the "laws of nature" that allow us to predict an object's motion?

Two key concepts that will help answer these questions are *force* (the "cause") and *acceleration* (the "effect"). Our basic tools will be three laws of motion worked out by Isaac Newton. Newton's laws relate force to acceleration, and we will use them to explain and explore a wide range of problems. As we learn to solve problems dealing with motion, we will learn basic techniques that we can apply in all the parts of this text.

### **Simplifying Models**

Another key aspect of physics is the importance of models. Suppose we want to analyze a ball moving through the air. Is it necessary to analyze the way the atoms in the ball are connected? Or the details of how the ball is spinning? Or the small drag force it experiences as it moves? These are interesting questions, of course. But if our task is to understand the motion of the ball, we need to simplify!

We can conduct a perfectly fine analysis of the ball's motion if we treat the ball as a single particle moving through the air. This is a *model* of the situation. A model is a simplified description of reality that is used to reduce the complexity of a problem so it can be analyzed and understood. Model building is a major part of the strategy that we will develop for solving problems throughout the text. Learning how to simplify a situation is the essence of successful modeling—and successful problem solving.

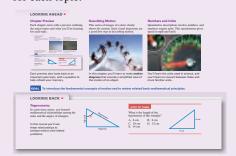
# Representing Motion



### **LOOKING AHEAD**

### **Chapter Preview**

Each chapter starts with a preview outlining the major topics and what you'll be learning for each topic.



Each preview also looks back at an important past topic, with a question to help refresh your memory.

### **Describing Motion**

This series of images of a skier clearly shows his motion. Such visual depictions are a good first step in describing motion.



In this chapter, you'll learn to make motion diagrams that provide a simplified view of the motion of an object.

### **Numbers and Units**

Quantitative descriptions involve numbers, and numbers require units. This speedometer gives speed in mph and km/h.



You'll learn the units used in science, and you'll learn to convert between these and more familiar units.

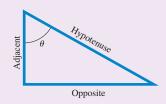
GOAL To introduce the fundamental concepts of motion and to review related basic mathematical principles.

### **LOOKING BACK**

### **Trigonometry**

In a previous course, you learned mathematical relationships among the sides and the angles of triangles.

In this course you'll use these relationships to analyze motion and related problems.



### STOP TO THINK

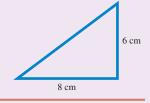
What is the length of the hypotenuse of this triangle?

A. 6 cm

B. 8 cm

C. 10 cm E. 14 cm

D. 12 cm



### 1.1 Motion: A First Look

Motion is a theme that will appear in one form or another throughout this entire text. You have a well-developed intuition about motion based on your experiences, but we'll find that some of the most important aspects of motion can be rather subtle. We need to develop some tools to help us explain and understand motion, so rather than jumping immediately into a lot of mathematics and calculations, this first chapter focuses on *visualizing* motion and becoming familiar with the *concepts* needed to describe a moving object.

One key difference between physics and other sciences is how we set up and solve problems. We'll often use a two-step process to solve motion problems. The first step is to develop a simplified *representation* of the motion so that key elements stand out. For example, the photo of the falcon at the start of the chapter allows us to observe its position at many successive times. We will begin our study of motion by considering this sort of picture. The second step is to analyze the motion with the language of mathematics. The process of putting numbers on nature is often the most challenging aspect of the problems you will solve. In this chapter, we will explore the steps in this process as we introduce the basic concepts of motion.

### Types of Motion

As a starting point, let's define **motion** as the change of an object's position or orientation with time. Examples of motion are easy to list. Bicycles, baseballs, cars, airplanes, and rockets are all objects that move. The path along which an object moves, which might be a straight line or might be curved, is called the object's **trajectory**.

FIGURE 1.1 shows four basic types of motion that we will study in this text. In this chapter, we will focus on the first type of motion in the figure, motion along a straight line, or *straight-line motion*. In later chapters, we will learn about *circular motion*, which is the motion of an object along a circular path; *projectile motion*, the motion of an object through the air; and *rotational motion*, the spinning of an object about an axis.

FIGURE 1.1 Four basic types of motion.



Straight-line motion



Circular motion



**Projectile motion** 



**Rotational motion** 

### **Making a Motion Diagram**

An easy way to study motion is to record a video of a moving object with a stationary camera. A video camera takes images at a fixed rate, typically 30 images every second. Each separate image is called a *frame*. As an example, **FIGURE 1.2** shows several frames from a video of a car going past, with the camera in a fixed position. Not surprisingly, the car is in a different position in each frame.

FIGURE 1.2 Several frames from the video of a car.

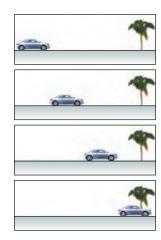


FIGURE 1.3 A motion diagram of the car shows all the frames simultaneously.



The same amount of time elapses between each image and the next.

Suppose we now edit the video by layering the frames on top of each other. We end up with the picture in **FIGURE 1.3**. This composite image, showing an object's positions at several *equally spaced instants of time*, is called a **motion diagram**. As simple as motion diagrams seem, they will turn out to be powerful tools for analyzing motion.

Now let's take our camera out into the world and make some motion diagrams. The following table illustrates how a motion diagram shows important features of different kinds of motion.

# Examples of motion diagrams Images that are equally spaced indicate an object moving with constant speed. A skateboarder rolling down the sidewalk. An increasing distance between the images shows that the object is speeding up. A sprinter starting the 100 meter dash. A decreasing distance between the images shows that the object is slowing down. A car stopping for a red light. A more complex motion diagram shows changes in speed and direction. A basketball free throw.

We have defined several concepts (constant speed, speeding up, and slowing down) in terms of how the moving object appears in a motion diagram. These are called **operational definitions**, meaning that the concepts are defined in terms of a particular procedure or operation. For example, we could answer the question Is the airplane speeding up? by checking whether the images in the plane's motion diagram are getting farther apart. Many of the concepts in physics will be introduced as operational definitions. This reminds us that physics is an experimental science.

STOP TO THINK 1.1 Which car is going faster, A or B? Assume there are equal intervals of time between the frames of both videos.



NOTE Each chapter in this text has several *Stop to Think* questions. These questions are designed to see if you've understood the basic ideas that have just been presented. The answers are given at the end of the chapter, but you should make a serious effort to think about these questions before turning to the answers.

### 1.2 Models and Modeling

The real world is messy and complicated. Our goal in studying physics is to brush aside many of the real-world details in order to discern patterns that occur over and over. For example, a swinging pendulum, a vibrating guitar string, a sound wave, and jiggling atoms in a crystal are all very different—yet they share a common core characteristic: Each is an example of an *oscillating system*, something that moves back and forth around an equilibrium position. If we focus on understanding a very simple oscillating system, such as a block (generically, a "mass") attached to a spring, we'll automatically understand quite a bit about the many real-world examples of oscillations.

Stripping away the details to focus on essential features is a process called *modeling*. A **model** is a highly simplified picture of reality, but one that still captures the essence of what we want to study. Thus a mass attached to a spring is a simple but realistic model of many oscillating systems.

Models allow us to make sense of complex situations by providing a framework for thinking about them. One could go so far as to say that developing and testing models is at the heart of the scientific process. Albert Einstein once said, "Physics should be as simple as possible—but not simpler." We want to find the simplest model that allows us to understand the phenomenon we're studying, but we can't make the model so simple that key aspects of the phenomenon get lost.

We'll develop and use many models throughout this text; they'll be one of our most important thinking tools. These models will be of two types:

- Descriptive models: What are the essential characteristics and properties of a phenomenon? How do we describe it in the simplest possible terms? For example, the mass-on-a-spring model of an oscillating system is a descriptive model.
- Explanatory models: Why do things happen as they do? Explanatory models, based on the laws of physics, have predictive power. They allow us to test—against experimental data—whether a model provides an adequate explanation of our observations. For example, the *charge model* that we will introduce in Chapter 20 helps us explain and predict a wide range of experimental outcomes related to electric forces.

When we solve physics problems, one of the most important steps is choosing an appropriate model for the system we are studying. In the worked examples in this text, in the first "Strategize" step, we'll point out the model being used, when appropriate.

### The Particle Model

For many objects, the motion of the object *as a whole* is not influenced by the details of the object's size and shape. To describe the object's motion, all we really need to keep track of is the motion of a single point: You could imagine looking at the motion of a dot painted on the side of the object.

In fact, for the purposes of analyzing the motion, we can often consider the object as if it were just a single point. We can also treat the object as if all of its mass were concentrated into this single point. An object that can be represented as a mass at a single point in space is called a **particle**.

If we treat an object as a particle, we can represent the object in each frame of a motion diagram as a simple dot. **FIGURE 1.4** shows how much simpler motion diagrams appear when the object is represented as a particle. Note that the dots have been numbered 0, 1, 2, . . . to tell the sequence in which the frames were exposed. These diagrams still convey a complete understanding of the object's motion.

In representing the car in Figure 1.4 as a particle, we have discarded many of the details of the car, such as the shape of its body and the motion of its wheels, which are unimportant in understanding its overall motion. In other words, we have developed a model for moving objects, the **particle model**, that allows us to see

FIGURE 1.4 Simplifying a motion diagram using the particle model.

(a) Motion diagram of a car stopping



(b) Same motion diagram using the particle model

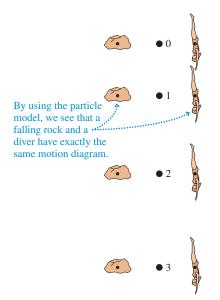
The same amount of time elapses between each frame and the next.



A video to support a section's topic is embedded in the eText.

Video Figure 1.4

FIGURE 1.5 The particle model for two falling objects.



connections that are very important but that are obscured or lost by examining all the parts of an extended, real object. Consider the motion of the rock and the diver shown in FIGURE 1.5. These two very different objects have exactly the same motion diagram. As we will see, all objects falling under the influence of gravity move in exactly the same manner if no other forces act. The simplification of the particle model has revealed something about the physics that underlies both of these situations

STOP TO THINK 1.2 Three motion diagrams are shown. Which is a dust particle settling to the floor at constant speed, which is a ball dropped from the roof of a building, and which is a descending rocket slowing to make a soft landing on Mars?

A. 0 ● 1 ●	B. 0 <b>●</b>	C. 0 ●
2 •	1 ●	
3 ●	2 ●	1 •
4 ●	3 ●	2 ●
	4 ●	3 ●
5 ●	5 ●	4 <b>●</b> 5 <b>●</b>

# 1.3 Position and Time: Putting Numbers on Nature

To develop our understanding of motion further, we need to be able to make quantitative measurements: We need to use numbers. As we analyze a motion diagram, it is useful to know where the object is (its *position*) and when the object was at that position (the *time*). We'll start by considering the motion of an object that can move only along a straight line. Examples of this **one-dimensional** or "1-D" motion are a car moving along a long, straight road; an airplane taxiing down a runway; and an elevator moving up and down a shaft.

### **Position and Coordinate Systems**

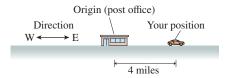
Suppose you are driving along a long, straight country road, as in FIGURE 1.6, and your friend calls and asks where you are. You might reply that you are 4 miles east of the post office, and your friend would then know just where you were. Your location at a particular instant in time (when your friend phoned) is called your **position**. Notice that to know your position along the road, your friend needed three pieces of information. First, you had to give her a reference point (the post office) from which all distances are to be measured. We call this fixed reference point the **origin**. Second, she needed to know how far you were from that reference point or origin—in this case, 4 miles. Finally, she needed to know which side of the origin you were on: You could be 4 miles to the west of it or 4 miles to the east.

We will need these same three pieces of information in order to specify any object's position along a line. We first choose our origin, from which we measure the distance to the object. The position of the origin is arbitrary, and we are free to place it where we like. Usually, however, there are certain points (such as the well-known post office) that are more convenient choices than others.

In order to specify how far our object is from the origin, we lay down an imaginary axis along the line of the object's motion. Like a ruler, this axis is marked off in equally spaced divisions of distance, perhaps in inches, meters, or miles, depending on the problem at hand. We place the zero mark of this ruler at the origin, allowing us to locate the position of our object by reading the ruler mark where the object is.

Finally, we need to be able to specify which side of the origin our object is on. To do this, we imagine the axis extending from one side of the origin with increasing

FIGURE 1.6 Describing your position.





This gauge's vertical scale measures the depth of snow when it falls. It has a natural origin at the level of the road.

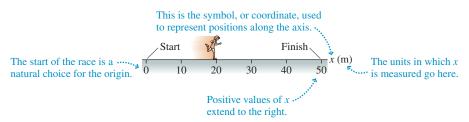
positive markings; on the other side, the axis is marked with increasing *negative* numbers. By reporting the position as either a positive or a negative number, we know on what side of the origin the object is.

These elements—an origin and an axis marked in both the positive and negative directions—can be used to unambiguously locate the position of an object. We call this a **coordinate system**. We will use coordinate systems throughout this text, and we will soon develop coordinate systems that can be used to describe the positions of objects moving in more complex ways than just along a line. **FIGURE 1.7** shows a coordinate system that we can use to locate various objects along the country road discussed earlier.

Although our coordinate system works well for describing the positions of objects located along the axis, our notation is somewhat cumbersome because we keep needing to say things like "the car is at position +4 miles." A better notation, and one that will become particularly important when we study motion in two dimensions, is to use a symbol such as x or y to represent the position along the axis. Then we can say "the cow is at x = -5 miles." The symbol that represents a position along an axis is called a **coordinate**. The introduction of symbols to represent positions (and, later, velocities and accelerations) also allows us to work with these quantities mathematically.

FIGURE 1.8 shows how we would set up a coordinate system for a sprinter running a 50 meter race (we use the standard abbreviation "m" for meters). For horizontal motion like this we usually use the coordinate *x* to represent the position.

FIGURE 1.8 A coordinate system for a 50 meter race.



Motion along a straight line need not be horizontal. As shown in **FIGURE 1.9**, a rock falling vertically downward and a skier skiing down a straight slope are also examples of straight-line or one-dimensional motion.

### **Time**

The pictures in Figure 1.9 show the position of an object at just one instant of time. But a full motion diagram represents how an object moves as time progresses. So far, we have labeled the dots in a motion diagram by the numbers 0, 1, 2, . . . to indicate the order in which the frames were taken. But to fully describe the motion, we need to indicate the *time*, as read off a clock or a stopwatch, at which each frame of a video was made. This is important, as we can see from the motion diagram of a stopping car in FIGURE 1.10. If the frames were taken 1 second apart, this motion diagram shows a leisurely stop; if 1/10 of a second apart, it represents a screeching halt.

For a complete motion diagram, we thus need to label each frame with its corresponding time (symbol t) as read off a clock. But when should we start the clock? Which frame should be labeled t=0? This choice is much like choosing the origin x=0 of a coordinate system: You can pick any arbitrary point in the motion and label it "t=0 seconds." This is simply the instant you decide to start your clock or stopwatch, so it is the origin of your time coordinate. A video frame labeled "t=4 seconds" means it was taken 4 seconds after you started your clock. We typically choose t=0 to represent the "beginning" of a problem, but the object may have been moving before then.

FIGURE 1.7 The coordinate system used to describe objects along a country road.

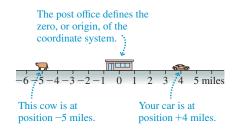


FIGURE 1.9 Examples of one-dimensional motion.

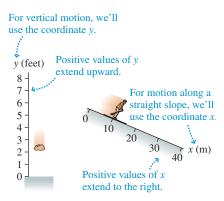


FIGURE 1.10 Is this a leisurely stop or a screeching halt?

